# Stratifications of hyperelliptic Jacobians and the Sato Grassmannian 

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#### Abstract

In this paper, a one-dimensional family of stratifications on a hyperelliptic Jacobian is introduced. It generalizes a well-known stratification, considered in algebraic geometry, in the context of special divisors. The stratification is shown to be related to a natural stratification on the Sato Grassmannian, via an extension of Krichever's map. It is also related to the stratification associated to the Laurent solutions of certain vector fields which can both be seen as living on the Grassmannian or on the Jacobian.


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## 1. Introduction

In this paper we introduce a one-dimensional family of stratifications on the Jacobian of any hyperelliptic curve and show how it appears naturally in different situations. Some stratifications of Abelian varieties, in particular of Jacobians, have been used and studied in algebraic geometry, in connection with linear systems of (special) divisors on curves. For example, let $\Gamma$ be a hyperelliptic curve with hyperelliptic involution $P \mapsto P^{\sigma}$ and let $P$ be a Weierstraß point on it. Then Gunning (see [Gu]) considers, for $m=0, \ldots, g$, the subsets $J_{m}(\Gamma, P)$ of the Jacobian of $\Gamma, \operatorname{Jac}(\Gamma)$, defined by

$$
J_{m}(\Gamma, P)=\left\{\{D\} \mid D=\sum_{i=1}^{g-m}\left(P_{i}-P\right), P_{i} \in \Gamma \backslash\{P\}, i \neq j \Rightarrow P_{i} \neq \imath P_{j}\right\}
$$

where $\{D\}$ denotes the class of all divisors linearly equivalent to $D$, viewed as a point of $\operatorname{Jac}(\Gamma)$. He shows that they define a stratification of the Jacobian of $\Gamma$.

This stratification generalizes in a natural way, specific to hyperelliptic Jacobians, to the case where $P$ is any point on the curve $\Gamma$. If the point corresponding to $P$ under the hyperelliptic involution is denoted by $P^{\sigma}$, then we define for $m$ and $n$ positive, $m+n \leq g=$ genus $(\Gamma)$,
$J_{m, n}(\Gamma, P)=\left\{\{D\} \mid D=\sum_{i=1}^{g-m-n} P_{i}+m P+n P^{\sigma}-g P, P_{i} \in \Gamma \backslash\left\{P, P^{\sigma}\right\}\right.$ and $\left.i \neq j \Rightarrow P_{i} \neq P_{j}^{\sigma}\right\}$.
Remark that in the case $P=P^{\sigma}$ considered by Gunning, one has $J_{m}(\Gamma, P)=J_{m-i, i}(\Gamma, P)$ for any $i \leq m$. In the opposite case $P \neq P^{\sigma}$, however, all $J_{m, n}(\Gamma, P)$ are disjoint and we show that they stratify $\operatorname{Jac}(\Gamma)$, with $i+1$ strata of codimension $i$, (in total $\frac{(g+1)(g+2)}{2}$ strata) and it is shown how they relate. If the chosen point $P \in \Gamma$ is replaced by $P^{\sigma}$, then one obviously obtains the same stratification, up to a translation; therefore the family of stratifications is essentially parametrized by $\Gamma / \sigma$, i.e., by $\mathbb{P}^{1}$.

It is easily deduced from [SW] that the stratification considered by Gunning arizes in the context of an infinite-dimensional Grassmannian, Gr, introduced by Sato (see [SS]). The Grassmannian Gr can be defined as the set of all linear spaces of formal power series in one variable $z$ (which should be thought of as being large) which have an algebraic basis of the form

$$
\left\{w_{0}(z), w_{1}(z), w_{2}(z), \ldots\right\}
$$

where

$$
w_{i}(z)=\sum_{j=-\infty}^{s_{i}} w_{i j} z^{j}, \quad w_{i s_{i}} \neq 0 \text { and } s_{i}<s_{i+1},
$$

with $i=s_{i}$ for $i$ sufficiently large. To such a linear space $W \in \mathrm{Gr}$ there is associated the (ordered) subset $S_{W}=\left\{s_{0}, s_{1}, \ldots,\right\}$ of the integers, which has the property that $s_{i}=i$ for $i$ sufficiently large. Each such sequence defines in a natural way a (nonempty) subset $\Sigma_{S} \subset \mathrm{Gr}$, defined as

$$
\Sigma_{S}=\left\{W \in \mathrm{Gr} \mid S_{W}=S\right\}
$$

These (nonintersecting) subsets can be shown to be the strata of a stratification of Gr (see [PS]). To relate this stratification to Gunning's stratification, the Krichever map is used. Roughly speaking, this map associates to a point in the Jacobian of $\Gamma$, that is, to a line bundle on $\Gamma$, the family of all its sections, which are holomorphic except at the marked point $P \in \Gamma$. This family is identified
with an element of Gr by using a trivialization of the line bundle. We remark that although this element of Gr depends on the trivialization, the stratum it belongs to is independent of it, hence we may use the Krichever map to relate both stratifications: we show that (different) strata are mapped into (different) strata so that we may think of the stratifications considered by Gunning as being induced by the natural stratification of Gr via the Krichever map.

The natural question arizes whether the stratifications by the subsets $J_{m, n}(\Gamma, P)$ can for every $P \in \Gamma$ be obtained in this way by an appropriate generalization of the Krichever map. The answer is affirmative and the generalized Krichever map which we introduce, associates now to each point in $\operatorname{Jac}(\Gamma)$ two points in Gr , i.e., a point in the product $\mathrm{Gr} \times \mathrm{Gr}$, which is equipped with the product stratification. In the special case that $P=P^{\sigma}$ the map reduces to a diagonal map (i.e., both points are the same) giving the ordinary Krichever map on each component. We also show that the stratification on $\mathrm{Gr} \times \mathrm{Gr}$ can be weakened to a coarser stratification, which still induces the family of stratifications. This coarser stratification shows up when considering the so-called K-P hierarchy on the Grassmannian (see [SS], [SW] and [DKJM]).

This K-P hierarchy, in particular a distinguished vector field of it, determines a special family of vector fields on $\operatorname{Jac}(\Gamma)$, depending on the marked point $P$ on $\Gamma$. As is well-known from the theory of integrable systems, every meromorphic function on $\operatorname{Jac}(\Gamma)$ admits families of Laurent solutions describing the function on the integral curves of the vector field (see [AvM3]). Taking one or several functions a decomposition of $\operatorname{Jac}(\Gamma)$ is given by fixing the way these solutions blow up. This decomposition may be a stratification. We will show that the choice of the very special vector field coming from the K-P hierarchy and a natural choice of functions coming from the symmetric functions on the curve, gives for each choice of the marked point $P$ on the curve, indeed a stratification which coincides again with the stratification by the subset $J_{m, n}(\Gamma, P)$, thereby providing us with a very explicit description of the former stratifications; in particular the leading behaviour of the Laurent solutions to the differential equations which describe the vector field will be computed explicitely by introducing a pair of tau functions which corresponds to the extended Krichever map.

The text is organized as follows. In Section 2 some preliminaries about hyperelliptic curves and their Jacobians are recalled and our family of stratifications is introduced. We give a detailed description of these stratifications since they are fundamental for the whole paper. Section 3 deals with the Sato Grassmannian, which is also recalled, together with its stratification. The Krichever map is explained and extended as needed for our purposes, leading to the main result relating the two stratifications. In the end the coarser stratification is discussed in the context of the K-P hierarchy. In the final Section 4, we look at special vector fields on the Jacobian, associated to a point on the curve; the relation between Laurent solutions to the vector field and stratifications of the Jacobian is explained and related to the stratification in Section 2, relying heavily on some results obtained in Section 3.

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## 2. The algebraic description of the stratification

In this section we introduce a natural family of stratifications on the Jacobian of a hyperelliptic curve, parametrized by a point on the curve. In the first paragraph we recall some basic results about hyperelliptic curves and their Jacobians (see [GH] or [H]). The stratification is introduced in the second paragraph and its structure is described.

### 2.1. Preliminaries

Let $\Gamma$ be a smooth (complete, irreducible) complex curve of genus $g$ which is hyperelliptic, i.e., $\Gamma$ it admits a $2: 1$ holomorphic cover $\pi: \Gamma \rightarrow \mathbb{P}^{1}$, which by the Riemann-Hurwitz formula is ramified over $2 g+2$ points, the so-called Weierstraß points of $\Gamma$. They are characteristic points of $\Gamma$ since they are precisely the fixed points of the unique (independent of $\pi$ ) holomorphic involution $\sigma: \Gamma \rightarrow \Gamma, Q \mapsto \sigma(Q)=Q^{\sigma}, \sigma^{2}=$ Id which interchanges the sheets of $\pi$, the so-called hyperelliptic involution. The cover $\pi$ gives rise to an equation $y^{2}=f(x)$ for (an affine part of) $\Gamma$; the degree of $f$ is $2 g+1$ or $2 g+2$ according to whether or not $\infty \in \mathbb{P}^{1}$ is the image of a Weierstraß point, i.e., according to whether $\pi^{-1}(\infty)$ contains one point (with multiplicity two), or two points. These two points correspond under $\sigma$, which is given in terms of the coordinates $x, y$ by $(x, y) \mapsto(x,-y)$, in particular the Weierstraß points (lying in the affine part) have coordinates ( $x_{i}, 0$ ), where $x_{i}$ are the roots of $f$.

The group of divisors $D=\sum_{\text {finite }} c_{i} P_{i}\left(P_{i} \in \Gamma\right)$ on $\Gamma$ is denoted by $\operatorname{Div}(\Gamma)$ and $\sigma$ extends linearly to $\operatorname{Div}(\Gamma)$ giving an involution $D \mapsto D^{\sigma}$. There is associated to each meromorphic function $f \in \mathcal{M}(\Gamma)$ its divisor of zeroes minus its divisor of poles, denoted by ( $f$ ); obviously the map $(\cdot): \mathcal{M}(\Gamma) \rightarrow \operatorname{Div}(\Gamma)$ is a homomorphism. In the same way $(\omega)$ is defined for any meromorphic differential and one has $(f \omega)=(f)+(\omega)$. For example, let $P \in \Gamma$ and let

$$
y^{2}=f(x)=\prod_{i=1}^{\operatorname{deg} f}\left(x-x\left(B_{i}\right)\right)
$$

be an equation for $\Gamma$ such that $x(P)=\infty$. Then

$$
\begin{equation*}
(y)=\sum_{i=1}^{\operatorname{deg} f} B_{i}-\frac{\operatorname{deg} f}{2}\left(P+P^{\sigma}\right) \text { and }(x)=\sum_{i=1}^{2}\left(0,(-1)^{i} \sqrt{f(0)}\right)-\left(P+P^{\sigma}\right) . \tag{1}
\end{equation*}
$$

Also

$$
\begin{equation*}
(d x)=\sum_{i=1}^{2 g+1} B_{i}-3 P \text { or }(d x)=\sum_{i=1}^{2 g+2} B_{i}-2\left(P+P^{\sigma}\right) \tag{2}
\end{equation*}
$$

according to whether $P=P^{\sigma}$ or $P \neq P^{\sigma}$ (in that order).
We introduce the spaces $L(D)$ and $\Omega(D)$ for $D \in \operatorname{Div}(\Gamma)$ as

$$
\begin{aligned}
& L(D)=\{f \mid f \text { meromorphic function on } \Gamma \text { and }(f)+D \geq 0\}, \\
& \Omega(D)=\{\omega \mid \omega \text { meromorphic differential on } \Gamma \text { and }(\omega)+D \geq 0\} .
\end{aligned}
$$

Their dimensions are related by the Riemann-Roch formula which states (for algebraic curves) that for any $D \in \operatorname{Div}(\Gamma)$,

$$
\begin{equation*}
\operatorname{dim} L(D)=\operatorname{dim} \Omega(-D)-g+1+\operatorname{deg}(D) \tag{3}
\end{equation*}
$$

the degree $\operatorname{deg}(D)$ of a divisor $D$ being defined as $\operatorname{deg}\left(\sum c_{i} P_{i}\right)=\sum c_{i}$. In particular, since every holomorphic function on $\Gamma$ is constant, the space $\Omega=\Omega(0)$ of holomorphic differentials has dimension $g$ and by (1) and (2) has in the hyperelliptic case a basis

$$
\begin{equation*}
\left\{\frac{d x}{y}, \frac{x d x}{y}, \ldots, \frac{x^{g-1} d x}{y}\right\} \tag{4}
\end{equation*}
$$

when $y^{2}=f(x)$ is an equation for $\Gamma$ as above. Remark that it follows from (3) and (4) that if $P_{i}(i=1, \ldots, n \leq g)$ are such that $i \neq j \Rightarrow P_{i} \neq P_{j}^{\sigma}$ then

$$
\begin{equation*}
\operatorname{dim} \Omega\left(\sum_{i=1}^{n} P_{i}\right)=g-n \tag{5}
\end{equation*}
$$

For their meromorphic analogues with poles at $P$ and $P^{\sigma}$ only we have

$$
\begin{equation*}
\operatorname{dim} \Omega\left(k P+l P^{\sigma}\right)=g+k+l-1 \text { for } k>0, l \geq 0 \tag{6}
\end{equation*}
$$

To see this in case $P \neq P^{\sigma}$, first remark that (1) and (2) imply that $x^{i} d x$ has a pole of order $i+2$ at $P$ and at $P^{\sigma}$ (and no other poles), while $x^{g+i} d x / y$ has at these points poles of order $i+1$. This gives one differential form with a single pole at $P$ and $P^{\sigma}$ and for any $n>1$ two differential forms with a pole of order $n$ at these points. Since the first set of forms is even with respect to $\sigma$ and the other set is odd they are all independent (and independent from the holomorphic differentials). They are maximal independent, since having another independent form with poles only at $P$ and $P^{\sigma}$ would result in having a meromorphic differential form with a single pole, which contradicts the fact that the sum of the residues of a differential form over all its singular points is always 0 . This leads to (6) in case $P \neq P^{\sigma}$, the proof for the case $P=P^{\sigma}$ is very similar.

On the group $\operatorname{Div}(\Gamma)$ one introduces the notion of linear equivalence by $D \sim_{l} D^{\prime}$ iff $D-D^{\prime}=(f)$ for some meromorphic function $f$ on $\Gamma$ and the class of $D$ is written as $\{D\}$. The homomorphism deg descends to a homomorphism

$$
\operatorname{deg}_{l}: \frac{\operatorname{Div}(\Gamma)}{\sim_{l}} \rightarrow \mathbb{Z}
$$

 there is a very explicit description of the linear equivalence relation as we state in the following lemma (see [M]).

Lemma 1 Let $\Gamma$ be a hyperelliptic curve of genus $g$ with involution $\sigma$ and let $P \in \Gamma$ fixed. Then

1) $D_{1}+D_{1}^{\sigma} \sim_{l} D_{2}+D_{2}^{\sigma}$ for any $D_{1}, D_{2} \in \operatorname{Div}(\Gamma)$ of the same degree,
2) if $\sum_{i=1}^{g} P_{i} \sim_{l} \sum_{i=1}^{g} Q_{i}$, then $\sum_{i=1}^{g} P_{i}=\sum_{i=1}^{g} Q_{i}$ or $P_{i}=P_{j}^{\sigma}$ for some $i \neq j$,
3) if $\operatorname{deg} D=0$ then $D \sim_{l} \sum_{i=1}^{g}\left(P_{i}-P\right)$ for some $P_{i} \in \Gamma$.

The notion of linear equivalence is natural in view of the basic relation between divisors and (holomorphic) line bundles on a smooth curve: if a divisor $D$ has local defining functions $\left(f_{\alpha}\right)_{\alpha \in I}$ for some cover $\left(U_{\alpha}\right)_{\alpha \in I}$ of the curve, then the transition functions of a line bundle $[D]$ are given by $f_{\alpha} / f_{\beta}$ on $U_{\alpha} \cap U_{\beta}$, and it is a fundamental fact that the line bundle [ $D$ ] is determined by the (linear) equivalence class $\{D\}$; also every line bundle is the line bundle of a divisor. To a meromorphic section $\varphi$ of $[D]$ there is associated its divisor $(\varphi)$ and there exists a section $\varphi$ for which $(\varphi)=D$; fixing such a section shows that $L(D)$ is isomorphic to the vector space of holomorphic sections of [ $D$ ], in particular these spaces have the same dimension.

Let the degree of a line bundle be defined as the degree of its corresponding divisor and denote for any $d \in \mathbb{Z}$ the set of all line bundles of degree $d$ by $\operatorname{Pic}^{d}(\Gamma)$. Then it follows that for any $d \in \mathbb{Z}$, $\operatorname{Pic}^{d}(\Gamma)$ is isomorphic to $\operatorname{Jac}(\Gamma)$ via $\{D\} \mapsto\left[D+\mathcal{D}_{d}\right]$ where $\mathcal{D}_{d}$ is any fixed divisor of degree $d$. Except for $d=0$ there is no canonical choice for $\mathcal{D}_{d}$; if however - as in the present paper - the curve has a marked point $P$ then one is led to the natural choice $\mathcal{D}_{d}=d P$, used exclusively in the sequel.

### 2.2. The stratification

We now introduce a decomposition of $\operatorname{Jac}(\Gamma)$ with respect to an arbitrary fixed point $P$ on the (hyperelliptic) curve $\Gamma$. Let $\mathcal{I}_{g}$ denote the set

$$
\mathcal{I}_{g}=\{(m, n) \in \mathbb{N} \times \mathbb{N} \mid 0 \leq m+n \leq g\}
$$

which we order by $(m, n) \leq\left(m^{\prime}, n^{\prime}\right)$ iff $m \leq m^{\prime}$ and $n \leq n^{\prime}$. Then for $(m, n) \in \mathcal{I}_{g}$ we define a subset $\operatorname{Div}_{m, n}(\Gamma, P)$ of $\operatorname{Div}(\Gamma)$ by

$$
\operatorname{Div}_{m, n}(\Gamma, P)=\left\{\sum_{i=1}^{g-m-n} P_{i}+m P+n P^{\sigma}-g P \mid P_{i} \in \Gamma \backslash\left\{P, P^{\sigma}\right\} \text { and } i \neq j \Rightarrow P_{i} \neq P_{j}^{\sigma}\right\}
$$

the term $g P$ is introduced here in order to make every element in $\operatorname{Div}_{m, n}(\Gamma, P)$ of degree 0 . We denote

$$
\operatorname{Div}_{0}(\Gamma, P)=\bigcup_{n=0}^{g} \bigcup_{m=0}^{g-n} \operatorname{Div}_{m, n}(\Gamma, P)
$$

and show in the following lemma that $\pi$ : $\operatorname{ker} \operatorname{deg} \rightarrow \operatorname{Jac}(\Gamma), D \mapsto\{D\}$ restricts to a bijection $\pi: \operatorname{Div}_{0}(\Gamma, P) \rightarrow \operatorname{Jac}(\Gamma)$.

## Lemma 2

1) For any $(m, n) \in \mathcal{I}_{g}$ the restriction of $\pi$ to $\operatorname{Div}_{m, n}(\Gamma, P)$ is injective.
2) If $P \neq P^{\sigma}$, then the subsets $\pi\left(\operatorname{Div}_{m, n}(\Gamma, P)\right),(m, n) \in \mathcal{I}_{g}$ are all disjoint.
3) If $P=P^{\sigma}$, then $\operatorname{Div}_{m+1, n}(\Gamma, P)=\operatorname{Div}_{m, n+1}(\Gamma, P)$ if $m+n+1 \leq g$. In this case the $g+1$ subsets $\pi\left(\operatorname{Div}_{m, 0}(\Gamma, P)\right), 0 \leq m \leq g$ are all disjoint.
4) $\pi\left(\operatorname{Div}_{0}(\Gamma, P)\right)=\operatorname{Jac}(\Gamma)$.

Proof
Let $(k, l) \leq(m, n)$ in $\mathcal{I}_{g}$ and suppose that $\pi(D)=\pi\left(D^{\prime}\right)$ where $D \in \operatorname{Div}_{m, n}(\Gamma, P)$ and $D^{\prime} \in \operatorname{Div}_{k, l}(\Gamma, P)$; if $P=P^{\sigma}$ we may suppose that $n=l=0$ by using the obvious identity $\operatorname{Div}_{m+1, n}(\Gamma, P)=\operatorname{Div}_{m, n+1}(\Gamma, P)$ (valid for $\left.m+n+1 \leq g\right)$. Then cancelling $k$ terms $P$ it follows that we are asked for a meromorphic function $f$ on $\Gamma$ with at most $g$ poles $P_{i}$, no two of which correspond under the hyperelliptic involution. Using (5) and the Riemann-Roch formula (3) the function $f$ must be constant, hence $D=D^{\prime}$. This proves 1) and 2), and since the first part of 3) is obvious, also 3).

To prove that $\pi\left(\operatorname{Div}_{0}(\Gamma, P)\right)=\operatorname{Jac}(\Gamma)$ we need to show that every divisor $D$ of degree zero is linearly equivalent to a divisor inside one of the sets $\operatorname{Div}_{m, n}(\Gamma, P)$. By Lemma $1, D \sim_{l} \sum_{i=1}^{g}\left(P_{i}-P\right)$, for some points $P_{i} \in \Gamma$, but by the same lemma every occurrence of $Q+Q^{\sigma}$ can, up to linear equivalence, be replaced by $P+P^{\sigma}$, hence is linearly equivalent to an element in one of the sets $\operatorname{Div}_{m, n}(\Gamma, P)$.

We now prove that the sets $J_{m, n}(\Gamma, P) \stackrel{\text { def }}{=} \pi\left(\operatorname{Div}_{m, n}(\Gamma, P)\right)\left(\right.$ or $J_{m}(\Gamma, P) \stackrel{\text { def }}{=} \pi\left(\operatorname{Div}_{m, 0}(\Gamma, P)\right)$ in case $P=P^{\sigma}$ ) define a stratification of $\operatorname{Jac}(\Gamma)$, meaning that they are disjoint differentiable manifolds, whose boundary is a finite union of lower-dimensional sets $J_{s, t}(\Gamma, P)$ (resp. $J_{s}(\Gamma, P)$ ). To this aim we first need to explain the differential, or even complex, structure of $\operatorname{Jac}(\Gamma)$; more details are found in [GH]. It is one of the oldest and most profound results in the theory of algebraic curves that $\operatorname{Jac}(\Gamma)$ has the structure of a complex (algebraic) torus $\mathbb{C}^{g} / \Lambda$, where $\Lambda$ is a lattice of maximal rank in $\mathbb{C}^{g}$. In fact, it was first defined as a complex torus and shown (by Abel) to correspond to the above definition. We sketch the construction of the analytic object. Choose a symplectic basis $A_{1}, \ldots, A_{g}, B_{1}, \ldots, B_{g}$ for $H_{1}(\Gamma, \mathbb{Z})$, i.e., a basis for which the intersection indices between the cycles obey $A_{i} \cdot A_{j}=B_{i} \cdot B_{j}=0$ and $A_{i} \cdot B_{j}=\delta_{i j}$. Let $\left\{\omega_{1}, \cdots, \omega_{g}\right\}$ be the normalized basis of holomorphic differentials for which $\int_{A_{i}} \omega_{j}=\delta_{i j}$. Then the $2 g$ columns of the matrix $\left(I_{g} Z\right)$, where $Z_{i j}=\int_{B_{i}} \omega_{j}$, define a discrete subgroup $\Lambda$ in $\mathbb{C}^{g}$, which turns out to be of maximal rank. The quotient $\mathbb{C}^{g} / \Lambda$ is therefore a complex torus, which is up to isomorphism independent of the choice of basis for $H_{1}(\Gamma, \mathbb{Z})$. To link this torus with $\operatorname{Jac}(\Gamma)$ defined above, one introduces the Abel map $\mathcal{A}: \operatorname{Jac}(\Gamma) \rightarrow \mathbb{C}^{g} / \Lambda$ by

$$
\mathcal{A}\left\{\sum_{i}\left(P_{i}-Q_{i}\right)\right\}=\left(\sum_{i} \int_{Q_{i}}^{P_{i}} \omega_{1}, \ldots, \sum_{i} \int_{Q_{i}}^{P_{i}} \omega_{g}\right) \quad(\bmod \Lambda)
$$

and proves that it is a well-defined isomorphism (Abel's Theorem).
The subsets $J_{m, n}(\Gamma, P)$ and $J_{m}(\Gamma, P)$ introduced above can thus be seen as subsets of a complex torus under the Abel isomorphism and we will identify them with their image, writing $J_{m, n}(\Gamma, P)$ for $\mathcal{A}\left(J_{m, n}(\Gamma, P)\right)$ since no confusion can arise. We show that they are submanifolds of the torus and fit together such that they define a stratification of it. We give separate theorems for the cases $P \neq P^{\sigma}$ and $P=P^{\sigma}$.

Theorem 3 If $P \neq P^{\sigma}$ then $\operatorname{Jac}(\Gamma)$ is stratified by the $(g-m-n)$-dimensional submanifolds $J_{m, n}(\Gamma, P)$, whose closure is given by the (finite) union

$$
\begin{equation*}
\bar{J}_{m, n}(\Gamma, P)=\bigcup_{(k, l) \geq(m, n)} J_{k, l}(\Gamma, P) \tag{7}
\end{equation*}
$$

Each stratum $J_{m, n}(\Gamma, P)$ has two boundary components which are translates of each other by

$$
\vec{e}=\mathcal{A}\left\{P^{\sigma}-P\right\}=\left(\int_{P}^{P^{\sigma}} \omega_{1}, \ldots, \int_{P}^{P^{\sigma}} \omega_{g}\right) \quad(\bmod \Lambda)
$$

More generally, all $i+1$ strata of dimension $g-i$ are translates of each other by $n \vec{e}$ for some $n \in\{1, \ldots, i\}$. The closures of the $(g-1)$-dimensional strata $J_{1,0}(\Gamma, P)$ and $J_{0,1}(\Gamma, P)$ are translates of the theta divisor and are tangent along their intersection $\bar{J}_{1,1}(\Gamma, P)$.

## Proof

We first show that each $J_{m, n}(\Gamma, P)$ is a submanifold of $\operatorname{Jac}(\Gamma)$ of dimension $g-m-n$. Let $d=g-m-n>0$ (otherwise there is nothing to prove) and consider the $d$-fold symmetric product of $\Gamma$ with itself, denoted $\operatorname{Sym}^{d} \Gamma$. This space is known to have a (complex) differential structure, with coordinates which derive from coordinates on $\Gamma$. Namely, on a neighbourhood of a generic point $\left\langle P_{1}, \ldots, P_{d}\right\rangle \in \operatorname{Sym}^{d} \Gamma$ for which all $P_{i}$ are distinct, the coordinates $z_{i}$ centered at $P_{i}$ serve as coordinates; when two or more of the $P_{i}$ coincide however, their corresponding coordinates need
to be replaced by the symmetric functions of these coordinates, for example, if $P_{1}=P_{2}$ then take $z_{1}+z_{2}$ and $z_{1} z_{2}$ instead of $z_{1}$ and $z_{2}$. It is clear that as a subset of the torus, $J_{m, n}(\Gamma, P)$ is given by the image of the (Abel map-like) map $\mathcal{A}_{s}$ defined by

$$
\mathcal{A}_{s}\left\langle P_{1}, \ldots, P_{d}\right\rangle=n \vec{e}+\left(\sum_{i=1}^{d} \int_{P}^{P_{i}} \omega_{1}, \ldots, \sum_{i=1}^{d} \int_{P}^{P_{i}} \omega_{g}\right) \quad(\bmod \Lambda),
$$

on the open set $\mathcal{U}_{d} \subset \operatorname{Sym}^{d} \Gamma$ for which all $P_{i} \notin\left\{P, P^{\sigma}\right\}$ and $i \neq j \Rightarrow P_{i} \neq P_{j}^{\sigma}$. Therefore it suffices to show that the Jacobian of this map is nowhere singular on $\mathcal{U}_{d}$. If the $g$ holomorphic differentials $\omega_{i}$ are written as $f\left(z_{j}\right) d z_{j}$ around $P_{j}$, then the Jacobian matrix of $\mathcal{A}_{s}$ has at the generic point $\left\langle P_{1}, \ldots, P_{d}\right\rangle$ entries $f_{i}\left(P_{j}\right)$ and its rank is maximal since otherwise there would be at least a $(g-r+1)$-dimensional family of holomorphic differentials vanishing at the $r$ points $P_{i}$ in contradiction with (5) and the domain of $\mathcal{A}_{s}$. If some of the points $P_{i}$ coincide we arrive at the same conclusion (including multiplicities): if, say, $P_{1}$ occurs $n$ times then the $i$ th column $(1 \leq i \leq n)$ of the matrix is to be replaced by the $(i-1)$ th derivative of $f_{i}$, evaluated at $P_{j}$; then the rank being not maximal would mean that there is a $(g-r+1)$-dimensional family of holomorphic differentials vanishing $n$ times at $P_{1}$ and vanishing simply at the other points, again in contradiction with (5).

We now compute the boundary $\bar{J}_{m, n}(\Gamma, P)$ of the strata $J_{m, n}(\Gamma, P)$. Since $\operatorname{Jac}(\Gamma)$ is given under the Abel isomorphism $\mathcal{A}$ the quotient topology coming from $\operatorname{Sym}^{g} \Gamma$, it is sufficient to compute the closure of each subset $J_{m, n}(\Gamma, P)$ for this topology (recall that we identified $J_{m, n}(\Gamma, P)$ with its image $\left.\mathcal{A}\left(J_{m, n}(\Gamma, P)\right)\right)$. Let us define the set

$$
K_{m, n}(\Gamma, P)=\left\{\sum_{i=1}^{g-m-n} P_{i}+m P+n P^{\sigma}-g P \mid P_{i} \in \Gamma\right\},
$$

which is compact since it is just $\operatorname{Sym}^{g-m-n} \Gamma$. By continuity of $\pi$, its image $\pi\left(K_{m, n}(\Gamma, P)\right)$ is also compact, hence closed; obviously it is contained in $\bar{J}_{m, n}(\Gamma, P)$ hence $\bar{J}_{m, n}(\Gamma, P)=\pi\left(K_{m, n}(\Gamma, P)\right)$; moreover

$$
\pi\left(K_{m, n}(\Gamma, P)\right)=\bigcup_{(k, l) \geq(m, n)} J_{k, l}(\Gamma, P)
$$

which proves (7).
Thus the different strata fit together as dictated by the partial order $\leq$ on $\mathcal{I}_{g}$ : if we represent the different spaces $\bar{J}_{m, n}(\Gamma, P)$ by $\bar{J}_{m, n}$, put those of equal dimension on the same horizontal line and depict inclusions by arrows, then we find the following.


Remark that the intersection of two spaces $\bar{J}_{m, n}(\Gamma, P)$ and $\bar{J}_{k, l}(\Gamma, P)$ is given by the set $\bar{J}_{s, t}(\Gamma, P)$ where $(s, t)$ is the supremum of $\{(k, l) \geq(m, n)\}$ (if it exists, otherwise the intersection is empty). Therefore it is read off immediately from the diagram as follows: if say $m \leq k$, then draw on the
diagram a diagonal line (of slope 1) through $\bar{J}_{m, n}$ and another one (of slope -1 ) through $\bar{J}_{k, l}$; then their intersection point (if any) corresponds to the intersection of these lines.

There is exactly one big stratum (i.e., a stratum of maximal dimension $g$ ) namely $J_{0,0}(\Gamma, P)$, and its boundary consists of two strata of codimension one, namely $\bar{J}_{1,0}(\Gamma, P)$ and $\bar{J}_{0,1}(\Gamma, P)$, and so on. Since

$$
\operatorname{Div}_{m+1, n}(\Gamma, P)=\operatorname{Div}_{m, n+1}(\Gamma, P)+P-P^{\sigma}
$$

if $m+n+1 \leq g$, the sets $\bar{J}_{1,0}(\Gamma, P)$ and $\bar{J}_{0,1}(\Gamma, P)$ are translates of each other by $\vec{e}=\mathcal{A}\left\{P^{\sigma}-P\right\}$, namely $\bar{J}_{0,1}(\bar{\Gamma}, P)=\bar{J}_{1,0}(\Gamma, P)+\vec{e}$, and it can be shown that they are translates of the theta divisor (see below). In general all strata $J_{m, n}(\Gamma, P)$ (except the zero-dimensional ones) have two boundary components, $\bar{J}_{m+1, n}(\Gamma, P)$ and $\bar{J}_{m, n+1}(\Gamma, P)$, which are obviously also translates of each other by $\vec{e}$. Therefore all sets $\bar{J}_{m, n}(\Gamma, P)$ of the same dimension $g-m-n$ are translates of each other by some integer multiple of $\vec{e}$, for example for the points $\bar{J}_{g, 0}(\Gamma, P)$ and $\bar{J}_{0, g}(\Gamma, P)$ it follows immediately that $\bar{J}_{0, g}(\Gamma, P)=\bar{J}_{g, 0}(\Gamma, P)+g \vec{e}$.

In [Gu] (Chapter 4, p. 143) explicit formulas are found for calculating the intersection of two translates of the theta divisor. These show that in general the intersection of two translates of the Riemann theta divisor is reducible and has two components. Since in our case $\bar{J}_{1,0}(\Gamma, P) \cap$ $\bar{J}_{0,1}(\Gamma, P)=\bar{J}_{1,1}(\Gamma, P)$ is irreducible, these components coincide, hence $\bar{J}_{1,0}(\Gamma, P)$ and $\bar{J}_{0,1}(\Gamma, P)$ are tangent along $\bar{J}_{1,1}(\Gamma, P)$.

The corresponding theorem for $P=P^{\sigma}$ is stated as follows and proven in the same way.
Theorem 4 If $P=P^{\sigma}$ then $\operatorname{Jac}(\Gamma)$ is stratified by the $(g-m)$-dimensional subsets $J_{m}(\Gamma, P)$, whose closure is given by the (finite) union

$$
\bar{J}_{m}(\Gamma, P)=\bigcup_{k \geq m} \bar{J}_{k}(\Gamma, P) .
$$

and each stratum $\bar{J}_{m}(\Gamma, P)$ has just one boundary component. Here the stratification is simply depicted as

$$
\bar{J}_{g} \rightarrow \bar{J}_{g-1} \rightarrow \bar{J}_{g-2} \rightarrow \cdots \rightarrow \bar{J}_{1} \rightarrow \bar{J}_{0}
$$

$\bar{J}_{0}=\operatorname{Jac}(\Gamma), \bar{J}_{1}$ is a translate of the theta divisor and $\bar{J}_{g}$ is the origin in $\operatorname{Jac}(\Gamma)$.

In Theorems 3 and 4 we claimed that $\bar{J}_{1,0}(\Gamma, P)$ and $\bar{J}_{1}$ were translates of the theta divisor; this is the divisor of the classical Riemann theta function for $\operatorname{Jac}(\Gamma)$, which is the entire function on $\mathbb{C}^{g}$ defined as

$$
\begin{equation*}
\theta(z)=\sum_{l \in Z^{g}} e^{\pi i\langle l, A l\rangle} e^{2 \pi i\langle l, z\rangle} \tag{8}
\end{equation*}
$$

when the lattice $\Lambda$ of $\operatorname{Jac}(\Gamma) \cong \mathbb{C}^{g} / \Lambda$ is written as $\left(I_{g} A\right)$. Remark that although $\theta$ is only defined on $\mathbb{C}^{g}$, the theta divisor is well-defined as its zero locus on $\operatorname{Jac}(\Gamma)$. Riemann showed (see $[\mathrm{M}]$ or [GH]) that there is a constant $\vec{\Delta} \in \mathbb{C}^{g}$ (called Riemann's constant) such that

$$
\begin{equation*}
\theta(Z)=0 \Longleftrightarrow \exists P_{1}, \ldots, P_{g-1} \in \Gamma: Z=\mathcal{A}\left\{\sum_{i=1}^{g-1}\left(P_{i}-P\right)\right\}-\vec{\Delta} \quad(\bmod \Lambda) . \tag{9}
\end{equation*}
$$

The important condition in the right-hand side is that the sum runs over $g-1$ points only. Formula (9) leads at once to the cited claims.

## 3. The Sato Grassmannian

We show in this section how the stratifications from the preceding section are induced by a natural stratification of the Sato Grassmannian via an extension of the Krichever map. In the first paragraph we recall from [SS], [SW] and [PS] the Sato Grassmannian, its stratification and the Krichever map, which relates the Grassmannian to algebraic curves. In the second paragraph, we introduce an extension of this map in the case of hyperelliptic curves and relate both stratifications. A coarser stratification of the Grassmannian is introduced in the last paragraph; it appears in a natural way when the K-P hierarchy is introduced on the Grassmannian.

### 3.1. The Grassmannian and its stratification

In this paragraph $\Gamma$ denotes any smooth curve of genus $g$ (i.e., $\Gamma$ needs not to be hyperelliptic), with a marked point $P$ on it. We also fix a small coordinate neighbourhood $(s, \mathcal{U})$ centered at $P$, for which $s(\mathcal{U})$ is the unit disk in $\mathbb{C}$. Then the boundary $\partial \mathcal{U}$ is diffeomorphic to a circle and $L^{2}(\partial \mathcal{U}, \mathbb{C})$ is a Hilbert space, with a basis

$$
\left\{\ldots, z^{-2}, z^{-1}, 1, z, z^{2}, \ldots\right\}
$$

where $z=s^{-1}$. The Hilbert space decomposes as $L^{2}(\partial \mathcal{U}, \mathbb{C})=\mathcal{H}_{+} \oplus \mathcal{H}_{-}$, where

$$
\mathcal{H}_{+}=\overline{\left\{1, z, z^{2}, \ldots\right\}} \text { and } \mathcal{H}_{-}=\overline{\left\{z^{-1}, z^{-2}, \ldots\right\}},
$$

(the closure is here the $L^{2}$-closure). Let Gr denote the set of all closed subspaces $W \subset L^{2}(\partial \mathcal{U}, \mathbb{C})$ which have an algebraic basis of the form $\left\{f_{i}\right\}_{i \in \mathbb{N}}$, with

$$
\begin{equation*}
f_{i}=\sum_{j=-\infty}^{s_{i}} c_{k} z^{k} \quad 0 \neq c_{s_{i}} \in \mathbb{C}, s_{i}<s_{i+1}, s_{i}=i \text { for } i \text { sufficiently large. } \tag{10}
\end{equation*}
$$

We call Gr the (Sato) Grassmannian of $L^{2}(\partial \mathcal{U}, \mathbb{C})$; it is a connected ${ }^{\dagger}$ Banach manifold, modelled on the Hilbert space of all Hilbert-Schmidt operators $\mathcal{H}_{+} \rightarrow \mathcal{H}_{-}$. For $f_{i}$ as in (10) we define its order to be $s_{i}$ and we associate to $W$ the (ordered) subset $S_{W}=\left\{s_{0}, s_{1}, s_{2}, \ldots\right\}$. We call such a subset of $\mathbb{Z}$ with $s_{i}<s_{i+1}$ and $s_{i}=i$ for $i$ sufficiently large, a sequence. The set of all points in Gr which have as sequence $S$ will be denoted by $\Sigma_{S}$,

$$
\Sigma_{S}=\left\{W \in \operatorname{Gr} \mid S_{W}=S\right\}
$$

We define a partial order on sequences by $S \leq S^{\prime}$ if the entries $s_{i}$ and $s_{i}^{\prime}$ of $S$ and $S^{\prime}$ satisfy $s_{i} \geq s_{i}^{\prime}$ for all $i \in \mathbb{N}$, and define the length $l(S)$ of a sequence $S$ as the finite sum $l(S)=\sum_{i \geq 0}\left(i-s_{i}\right)$. Then $S \leq S^{\prime}$ obviously implies $l(S) \leq l\left(S^{\prime}\right)$. Denoting by $U_{S}$ the set

$$
U_{S}=\left\{W \in \mathrm{Gr} \mid \operatorname{proj}\left(W \rightarrow \overline{\left\{z^{i} \mid i \in S\right\}}\right) \text { is an isomorphism }\right\}
$$

the stratification of Gr is described as follows (see [PS]).

[^0]Theorem 5 For any sequence $S$, the set $\Sigma_{S}$ is a closed subspace of $U_{S}$ and the collection of all $U_{S}$ forms an open cover of $G r$. The big stratum is given by $\Sigma_{\mathbb{N}}$ and all $\Sigma_{S}$ are smooth manifolds of codimension $l(S)$. The closure in $G r$ of each $\Sigma_{S}$ is the union of the strata $\Sigma_{S^{\prime}}$ for which $S^{\prime} \geq S$.

Sequences are in bijection with partitions. By a partition $\nu$ we mean a finite, nonincreasing sequence of positive integers $\nu_{0} \geq \nu_{1} \geq \cdots \geq \nu_{r} \geq 0$. The bijection is simply given by $\nu_{i}=i-s_{i}$ and we see that $l(S)=\sum_{i=0}^{r} \nu_{i}$. The sequence corresponding to a partition $\nu$ will be denoted by $S_{\nu}$. Also we define $l(\mu)=l\left(S_{\mu}\right)$ and $\mu \leq \nu$ iff $S_{\mu} \leq S_{\nu}$.

Partitions in turn are in bijection with Young diagrams, by which they are best visualized; a Young diagram is a finite (left aligned) arrangement of squares such that each row has at most as many squares as the preceding row and the Young diagram corresponding to $\nu_{0} \geq \nu_{1} \geq \cdots \geq \nu_{r} \geq 0$ is given by drawing $\nu_{i}$ squares in the $i$ th row. Then the number of squares in a Young diagram (called its weight) equals the length of its partition. For example, if $\nu$ is the partition $3 \geq 2 \geq 2 \geq 0$ then $S_{\nu}=\{-3,-1,0,3,4, \ldots\}$ and its Young diagram is drawn as follows.


We finally recall the Krichever map. The curve $\Gamma$, the point $P$ and a local parameter $s$ around $P$ being fixed, there is associated to a line bundle $\mathrm{L} \in \operatorname{Pic}^{g}(\Gamma)$ and a trivialization $\phi$ of L (say over a neighbourhood $\mathcal{V}$ of the closure of the coordinate neighbourhood $\mathcal{U}$ of $s$ ), a point $W(\mathrm{£}, \phi)$ in Gr as follows. Using $\phi$ we may think of sections of E over $\mathcal{V}$ as functions on $\mathcal{V}$, in particular such a section determines an element of $L^{2}(\partial \mathcal{U}, \mathbb{C})$. Then $W(\mathrm{£}, \phi)$ is defined as the closure of the set of all elements of $L^{2}(\partial \mathcal{U}, \mathbb{C})$ obtained in this way from meromorphic sections of E which are holomorphic away from $P$. Then the pole which the section has at $P$ coincides with the order of the section at $P$ and in particular is independent of the trivialization $\phi$. It follows that, although $W(\mathrm{~L}, \phi)$ depends on $\phi$, the stratum of Gr it belongs to is independent of $\phi$. Therefore the Krichever map induces a decomposition (possibly a stratification) of $\operatorname{Pic}^{g}(\Gamma)$, hence also of $\operatorname{Jac}(\Gamma)$. We will generalize the Krichever map in the case that $\Gamma$ is hyperelliptic to obtain a map which induces the stratifications on $\operatorname{Jac}(\Gamma)$ which we considered in the previous section.

### 3.2. Relating the stratifications

We now return to the case for which $\Gamma$ is hyperelliptic, $s$ a local parameter on a small neighbourhood $\mathcal{U}$ of a fixed point $P$; the Grassmannian built using these data is just denoted by Gr. For a point $\{D\} \in \operatorname{Jac}(\Gamma)$, let $\mathrm{L}_{+}$be the corresponding element in $\operatorname{Pic}^{g}(\Gamma)$ under our identification $\mathrm{Jac}(\Gamma) \xrightarrow{\otimes[g P]} \mathrm{Pic}^{g}(\Gamma)$, i.e., $\mathrm{L}_{+}=[D+g P]$ and let $\mathrm{E}_{-}=\mathrm{E}_{+} \otimes\left[P-P^{\sigma}\right]$; also choose a trivialization $\phi_{+}$of $\mathrm{E}_{+}$over $\mathcal{U}$ and choose a trivialization of $\mathrm{E}_{-}$as $\phi_{-}=\phi_{+} s$ if $P \neq P^{\sigma}$ and $\phi_{-}=\phi_{+}$otherwise. Then we obtain two points $W_{+}(D) \stackrel{\text { not }}{=} W\left(\mathrm{£}_{+}, \phi_{+}\right)$and $W_{-}(D) \stackrel{\text { not }}{=} W\left(\mathrm{£}_{-}, \phi_{-}\right)$, each belonging to a stratum which is independent of $\phi_{ \pm}$. Thus, $\Gamma, P$ and $(s, \mathcal{U})$ being fixed, there is associated to a point in $\operatorname{Jac}(\Gamma)$ and a trivialization of its line bundle a point in $\mathrm{Gr} \times \mathrm{Gr}$; if $P$ is a Weierstraß point,
then the image of this map is contained in the diagonal of $\mathrm{Gr} \times \mathrm{Gr}$ and we get the Krichever map; therefore we call our map an extension of the Krichever map. The two sequences of these strata will be denoted by $S_{+}(D)$ and $S_{-}(D)$, since they depend on $D$ only. We will show that the stratification of $\operatorname{Jac}(\Gamma)$ with respect to $P$, as defined in Section 2 is induced from the product stratification on $\mathrm{Gr} \times \mathrm{Gr}$ via this map.

Proposition 6 If $\operatorname{deg} D=0$ then the sequences $S_{+}(D)$ and $S_{-}(D)$ are computed as follows:

$$
\begin{aligned}
& S_{+}(D)=\{n \in \mathbb{Z} \mid \operatorname{dim} L(D+(g+n) P)>\operatorname{dim} L(D+(g+n-1) P)\} \\
& S_{-}(D)=\left\{n \in \mathbb{Z} \mid \operatorname{dim} L\left(D+(g+n+1) P-P^{\sigma}\right)>\operatorname{dim} L\left(D+(g+n) P-P^{\sigma}\right)\right\}
\end{aligned}
$$

## Proof

Since $\operatorname{deg} D=0,\{D\} \in J_{k, l}(\Gamma, P)$ for some $k, l \geq 0, k+l \leq g$. By Lemma $1,\{D\}$ is written as $\left\{D_{g}-g P\right\}$ for a unique $D_{g}=\sum_{i=1}^{g-m-n} P_{i}+m P+n P^{\sigma}$ of degree $g$, with $P_{i} \in \Gamma \backslash\left\{P, P^{\sigma}\right\}$, no two $P_{i}$ corresponding under $\sigma$. Let $\varphi$ be a holomorphic section of $\left[D_{g}\right]$ for which $(\varphi)=D_{g}$. Then the map $f \rightarrow \varphi f$ determines an isomorphism between the meromorphic functions on $\Gamma$ with (simple) poles on the points of $D_{g}$ and an arbitrary pole at $P$ on the one hand, and meromorphic sections of $\left[D_{g}\right]$, holomorphic away from $P$ at the other hand. Consequently we will find a function in $W_{+}(D)=W([D+g P], \phi)$ of order $n$ exactly when there exists a meromorphic function with poles on $D_{g}$ and a pole of order $n$ at $P$, i.e.,

$$
\begin{equation*}
n \in S_{+}(D) \text { iff } \operatorname{dim} L\left(D_{g}+n P\right)>\operatorname{dim} L\left(D_{g}+(n-1) P\right), \tag{11}
\end{equation*}
$$

which shows that $S_{+}(D)$ can be read off from the dimensions $\operatorname{dim} L\left(D_{g}+n P\right)$. The formula for $S_{-}(D)$ follows immediately from $S_{-}(D)=S_{+}\left(D+P-P^{\sigma}\right)$.

The following lemma will give us neat formulas to compute the sequences $S_{+}(D)$ and $S_{-}(D)$.
Lemma 7 Suppose there are given $n \leq g$ points $P_{1}, \ldots, P_{n} \in \Gamma \backslash\left\{P, P^{\sigma}\right\}$ such that $i \neq j \Rightarrow$ $P_{i} \neq P_{j}^{\boldsymbol{\sigma}}$. If $P \neq P^{\boldsymbol{\sigma}}$, let $D$ be a divisor of the form $D=\sum_{i=1}^{n} P_{i}+k P+l P^{\sigma}(k, l \in \mathbb{Z})$. Then $\operatorname{dim} L(D)$ is given by

$$
\operatorname{dim} L(D)=\left\{\begin{array}{l}
\max \{g-n-k-l-1,0\}+n+k+l+1-g \text { for } k<0 \text { or } l<0 \\
\max \{g-n-\max \{k, l\}, 0\}+n+k+l+1-g \text { for } k, l \geq 0
\end{array}\right.
$$

If alternatively $P=P^{\sigma}$, then $\operatorname{dim} L(D)$ is given for any divisor of the form $D=\sum_{i=1}^{n} P_{i}+k P$ $(k \in \mathbb{Z})$ by

$$
\operatorname{dim} L(D)=\left\{\begin{array}{l}
\max \{g-n-k-1,0\}+n+k+1-g \text { for } k<0 \\
\max \{g-n-\lceil k / 2\rceil, 0\}+n+k+1-g \text { for } k \geq 0
\end{array}\right.
$$

## Proof

We first consider the case $P \neq P^{\sigma}$. Let $D=\sum_{i=1}^{n} P_{i}+k P+l P^{\sigma}$ as above and suppose that $k<0$. Then by $(6), \operatorname{dim} \Omega(-k P)=g-k-1$. If $l$ is nonnegative, then the divisor $\sum P_{i}+l P^{\sigma}$ is of the form $\sum_{i=1}^{n+l} Q_{i}$ where $i \neq j \Rightarrow Q_{i} \neq Q_{j}^{\sigma}$, which amounts to $n+l$ linearly independent conditions. If $l$ is negative then by $(6), \operatorname{dim} \Omega\left(-k P-l P^{\sigma}\right)=g-k-l-1$ and there are $n$ linearly independent conditions coming from the points $P_{i}(i=1, \ldots, n)$. It follows as in (5) that in both cases there are
$g-n-k-l-1$ independent differentials in $\Omega(-D)$ as long as this number is positive, otherwise there are no such differentials. By Riemann-Roch,

$$
\begin{aligned}
\operatorname{dim} L(D) & =\operatorname{dim} \Omega(-D)+n+k+l+1-g \\
& =\max \{g-n-k-l-1,0\}+n+k+l+1-g,
\end{aligned}
$$

for $k<0$. The case $l<0$ is deduced from the above case by replacing $D$ by $D^{\sigma}$.
It remains to prove the case $k, l \geq 0$. Then we look for holomorphic differentials with zeroes at $n$ general points, with $k$ zeroes at $P$ and $l$ zeroes at $P^{\sigma}$. These are $n+k+l$ conditions, but since $\min \{k, l\}$ of them are the same, we arrive at $n+k+l-\min \{k, l\}=n+\max \{k, l\}$ independent conditions. It follows from (5) that we end up with $g-n-\max \{k, l\}$ differentials, as long this number is positive, otherwise there are no such differentials. Using Riemann-Roch again, we conclude

$$
\operatorname{dim} L(D)=\max \{g-n-\max \{k, l\}, 0\}+n+k+l+1-g
$$

for $k, l \geq 0$. This completes the proof in case $P \neq P^{\sigma}$.
Suppose now $P=P^{\sigma}$ and let $D=\sum_{i=1}^{n} P_{i}+k P$. If $k<0$ then it follows from (6) that $\operatorname{dim} \Omega(-k P)=g-k-1$. The $n$ points $P_{i}$ impose $n$ independent conditions on these differentials, giving $\operatorname{dim} \Omega\left(-\sum_{i=1}^{n} P_{i}-k P\right)=\max \{g-n-k-1,0\}$. Using Riemann-Roch we find

$$
\operatorname{dim} L(D)=\max \{g-n-k-1,0\}+n+k+1-g
$$

for $k<0$. If $k \geq 0$ then there are $g-\lceil k / 2\rceil$ holomorphic differentials in $\Omega(-k P)$ (as long as this number is positive), since in this case all the holomorphic differentials vanish to even order at $P$, as is seen from (1), (2) and (4). Therefore the dimension of $\Omega(-D)$ is given by $\max \{g-\lceil k / 2\rceil-n, 0\}$ and $L(D)$ is computed from the Riemann-Roch theorem as

$$
\operatorname{dim} L(D)=\max \{g-\lceil k / 2\rceil-n, 0\}+n+k+1-g
$$

for $k \geq 0$.
We combine Proposition 6 with the previous lemma to compute the sequences $S_{+}(D)$ and $S_{-}(D)$ and their Young diagrams. The basic relation between the stratifications of $\operatorname{Jac}(\Gamma)$ and $\mathrm{Gr} \times \mathrm{Gr}$ will follow immediately from it.

Theorem 8 Suppose $P \neq P^{\sigma}$ and $\{D\} \in J_{m, n}(\Gamma, P)$. Then $S_{+}(D)$ and $S_{-}(D)$ are sequences which depend only on the stratum (i.e., on $m$ and $n$ ) and are given by

$$
\begin{aligned}
& S_{+}(D)=\{-m, 1-m, 2-m, \ldots, n-m, n+1, n+2, n+3, \ldots\}, \\
& S_{-}(D)=\{-m-1,-m, 1-m, \ldots, n-m-2, n, n+1, \ldots\} .
\end{aligned}
$$

The corresponding Young diagrams are rectangles with $m$ columns and $n+1$ rows for $S_{+}(D)$ and $m+1$ columns and $n$ rows for $S_{-}(D)$, and their weights are simply given by $l\left(S_{+}(D)\right)=m(n+1)$ and $l\left(S_{-}(D)\right)=n(m+1)$. They look as follows.


Secondly, suppose that $P=P^{\sigma}$ and $\{D\} \in J_{m}(\Gamma, P)$. Then $S_{+}(D)=S_{-}(D)$ is a sequence which depends only on the stratum (i.e., on $m$ ) and is given by

$$
S_{+}(D)=\{-m, 2-m, 4-m, \ldots, m-2, m, m+1, m+2, \ldots\} .
$$

The corresponding Young diagram is a rotated stairs of height $m$, i.e., the first row has $m$ squares and every other row has one square less then the preceding row, hence it has weight $l\left(S_{+}(D)\right)=$ $\frac{m(m+1)}{2}$ and is depicted as follows.


Proof
Suppose at first that $P \neq P^{\sigma}$. For $D \in \operatorname{Div}_{m, n}(\Gamma, P)$ let $D_{g}=D+g P$, then by Lemma 7,

$$
\operatorname{dim} L\left(D_{g}+k P\right)=\max \{\min \{k+m, n\}, 0\}+1+k
$$

if $k+m \geq 0$, otherwise this dimension is zero. Since $S_{+}(D)=\left\{k \mid \operatorname{dim} L\left(D_{g}+k P\right)>\operatorname{dim} L\left(D_{g}+\right.\right.$ $(k-1) P)\}$ we see that

$$
S_{+}(D)=\{-m, 1-m, 2-m, \ldots, n-m, n+1, n+2, n+3, \ldots\} .
$$

Also, since $S_{-}(D)=S_{+}\left(D+P-P^{\sigma}\right)$ and since $D+P-P^{\sigma} \in \operatorname{Div}_{m+1, n-1}(\Gamma, P)$ if $n \geq 1$, the formula for $S_{-}(D)$ is found in this case by substituting $m+1$ for $m$ and $n-1$ for $n$ in the formula for $S_{+}(D)$. The proposed formula above for $S_{-}(D)$ gives for $n=0$, when properly interpreted, $S_{-}(D)=\mathbb{N}$. To see its validity, remark that in this case

$$
D_{g}+P-P^{\sigma}=\sum_{i=1}^{g-m} P_{i}+m P+P-P^{\sigma} \sim_{l} \sum_{i=1}^{g} Q_{i}
$$

for unique $Q_{i}$, all different from $P, P^{\sigma}$ and no two of which correspond under the hyperelliptic involution (using Lemma 1 again), hence $S_{-}(D)=\mathbb{N}$. The proof for $P=P^{\sigma}$ goes exactly along the same lines.
This theorem leads immediately to the main result of this section.
Theorem 9 The natural stratification of $\operatorname{Jac}(\Gamma)$ given by the subsets $J_{m, n}(\Gamma, P),(m, n) \in \mathcal{I}_{g}$, is induced by the (product) stratification on $G r \times G r$ given by the sets $\Sigma_{S} \times \Sigma_{T}$ ( $S, T$ sequences) via the "map"

$$
\begin{aligned}
F: \mathrm{Jac}(\Gamma) & \rightarrow G r \times G r \\
\{D\} & \mapsto\left(W_{+}(D), W_{-}(D)\right) .
\end{aligned}
$$

From the previous theorem it follows that the strata $J_{m, n}(\Gamma, P)$ are mapped into strata of the stratified space $\mathrm{Gr} \times \mathrm{Gr}$. Also it follows from this theorem that no two different strata $J_{m, n}(\Gamma, P)$ and $J_{m^{\prime}, n^{\prime}}(\Gamma, P)$ are mapped in the same stratum. To prove this it suffices to show that the numbers $(m, n) \in \mathcal{I}_{g}$ can be reconstructed from $S_{+}(D)$ and $S_{-}(D)$ (or equivalently from their Young diagrams). If both Young diagrams are empty then $(m, n)=(0,0)$. Otherwise $m$ and $n$ are found by counting rows and columns in one of the nonempty diagrams. Remark that for $m=0$ or $n=0$ it is essential to have both diagrams: the ordinary Krichever map is only able to distinguish the strata inside one of the two translates of the theta divisor. In the case $P=P^{\sigma}$ both Young diagrams are obviously the same (since $W_{+}(D)=W_{-}(D)$ ) and the theorem can be simplified using only the subsets $J_{m}(\Gamma, P)$ and the planes $W_{+}(D) \in$ Gr.

### 3.3. The K-P hierarchy on $\mathbf{G r}$ and another stratification

There is another stratification on Gr , (and on $\mathrm{Gr} \times \mathrm{Gr}$ ) coarser than the previous one, which shows up when a certain natural vector field on Gr is considered. Its strata consist of those points in Gr for which the associated Young diagrams have a given weight. To see that it is also a stratification, remark that each stratum is a finite union of the strata of the original stratification, and the boundary of a stratum now consists of those strata whose Young diagram has more weight than the Young diagram of the given stratum; we call it the coarser stratification (on Gr as well as on $\mathrm{Gr} \times \mathrm{Gr}$ where again the product stratification is considered). The following proposition follows at once from Theorem 8.

Proposition 10 The natural stratification of $\operatorname{Jac}(\Gamma)$ given by the subsets $J_{m, n}(\Gamma, P)$ is also induced by the coarser stratification on $G r \times G r$ via our extension of Krichever's map.
Proof
Clearly we only need to prove that no two strata are mapped in the same stratum. If $P=P^{\sigma}$, then the stratum which corresponds to $J_{m}(\Gamma, P)$ has weight $\frac{m(m+1)}{2}$, which is different for all $m \in \mathbb{N}$. If $P \neq P^{\sigma}$, then we need to reconstruct $m$ and $n$ from $w_{1}=m(n+1)$ and $w_{2}=n(m+1)$. However, given $w_{1}$ and $w_{2}$ there are only two solutions to this, namely $(m, n)$ and $(-n-1,-m-1)$, only one of which is positive.

The group $\mathbb{C}^{\infty}$ acts on Gr in an obvious way by $W \mapsto e^{-t_{n} z^{n}} W,\left(t_{n} \in \mathbb{C}\right)$, and its infinitimal action determines an infinite number of commuting vector fields $\partial / \partial t_{n}$ on Gr, called the $K-P$ hierarchy (this hierarchy can be written down in many equivalent forms, see [DKJM], [SS] and [SW]). The point $e^{-\sum_{j=1}^{\infty} t_{j} z^{j}} W$ is denoted by $W^{t}$, in particular $W=W^{0}$. It leads to the so-called tau function, also introduced by Sato (see [SS] and [SW]), which is defined for a generic point $W \in \mathrm{Gr}$ by

$$
\tau_{W}(t)=\frac{\sigma\left(W^{t}\right)}{e^{-\sum_{j=1}^{\infty} t_{j} z^{j}} \sigma(W)}=\frac{\sigma\left(e^{-\sum_{j=1}^{\infty} t_{j} z^{j}} W\right)}{e^{-\sum_{j=1}^{\infty} t_{j} z^{j}} \sigma(W)} .
$$

Here $\sigma(W)$ is a canonical global section of the dual Det* of the determinant bundle Det over Gr, which can be defined - with some care - as one defines the determinant bundle over a finite dimensional manifold. For a point for which $\sigma(W)=0$, this section is replaced by another (nonvanishing) section of Det ${ }^{\star}$. It is a fundamental fact that in the case $W=W(\mathrm{~L}, \phi)$ as in the previous paragraph, one has $W^{t}(\mathrm{~L}, \phi)=W\left(\mathrm{~L} \otimes \zeta_{t}, \phi_{t}\right)$ where $\zeta_{t}$ is the line bundle defined by the transition function $e^{\sum_{j=1}^{\infty} t_{j} s^{-j}}$ on the overlap of $\mathcal{W}=\Gamma \backslash\{P\}$ and $\mathcal{U}$; moreover, $t \mapsto \zeta_{t}$ defines a surjective homomorphism (see $[\mathrm{Sh}]$ ). It follows that $\mathbb{C}^{\infty}$ acts on the set $\operatorname{Pic}^{g}(\Gamma)$ by tensoring
with $\zeta_{t}$, hence the vector fields $\partial / \partial t_{n}$ give linear vector fields on any Jacobian $\operatorname{Jac}(\Gamma)$ under our identification with $\operatorname{Pic}^{g}(\Gamma)$ by $\{D\} \leftrightarrow[D+g P]$.

We apply this to our case in which $\Gamma$ is hyperelliptic, and we concentrate on the vector field $\partial / \partial t_{1}$. As before, $s$ is a local parameter around $P \in \Gamma$. Consider the inclusion

$$
\imath_{P}: \Gamma \rightarrow \mathrm{Jac}(\Gamma): Q \mapsto\{Q-P\} .
$$

Then $\partial / \partial t_{1}$, as a vector field on $\operatorname{Jac}(\Gamma)$ has the following property.
Proposition 11 The first K-P vector field $\partial / \partial t_{1}$, considered as a vector field on $\operatorname{Jac}(\Gamma)$, is tangent to the curve $\imath_{P}(\Gamma)$ at the origin of $\operatorname{Jac}(\Gamma)$.
Proof
Let $t=\left(t_{1}, 0,0, \ldots\right)$ with $t_{1}$ small. The line bundle in $\operatorname{Pic}^{g}(\Gamma)$ corresponding to the origin of $\mathrm{Jac}(\Gamma)$ is $\mathrm{L}=[g P]$, with transition functions $g_{\mathcal{U}} \mathcal{W}=s^{g}(\mathcal{W}=\Gamma \backslash\{P\})$, hence $\mathrm{L}_{t}=[g P] \otimes \zeta_{t}$ has transition functions

$$
g_{\mathcal{U W}}^{t}=s^{g} \exp \left(-t_{1} / s\right)=s^{g-1}\left(s-t_{1}\right)+\mathcal{O}\left(t_{1}^{2}\right),
$$

and since $t_{1}$ is small, the divisor corresponding to it (up to $\mathcal{O}\left(t_{1}^{2}\right)$ ) is $(g-1) P+P_{t_{1}}$, where $P_{t_{1}}$ is the point in $\mathcal{U}$ for which $s=t_{1}$. As a point in the Jacobian this is the point $\left\{P_{t_{1}}-P\right\}$ on the embedded curve $\imath_{P}(\Gamma)$. Therefore, around $P, \imath_{P}(\Gamma)$ coincides with the integral curve (which is just a straight line in the torus) of $\partial / \partial t_{1}$ at least to first order, hence they are tangent. The components of this vector in the direction of the holomorphic differentials $x^{k} d x / y,(k=0, \ldots, g-1)$ are easily computed; take for example $P=P^{\sigma}$ then $x=s^{-2}, y=s^{-2 g-1}+\mathcal{O}\left(s^{-2 g}\right)$ hence,

$$
\begin{equation*}
\lim _{t_{1} \rightarrow 0} \frac{1}{t_{1}} \int_{P}^{P_{t_{1}}} \frac{x^{k} d x}{y}=-2 \lim _{s \rightarrow 0} \frac{1}{s} \int_{0}^{s} s^{2(g-k-1)}(1+\mathcal{O}(s)) d s=-2 \delta_{k, g-1} \tag{12}
\end{equation*}
$$

Of interest to us is also how the tau function, associated to $W \in \mathrm{Gr}$, vanishes in the $t_{1}$-direction. This is given by the following proposition, due to [SW].

Proposition 12 For any $W \in G r$,

$$
\tau_{W}\left(t_{1}, 0,0, \ldots\right)=c t_{1}^{l}+\mathcal{O}\left(t_{1}^{l+1}\right)
$$

where $c \neq 0$ and $l$ is the codimension of the stratum of $G r$ containing $W$, i.e., it is the weight $l\left(S_{W}\right)$ of the Young diagram of $W$.

Having associated two points $W_{+}(D)$ and $W_{-}(D)$ to a point $\{D\}$, we have also two corresponding tau functions $\tau_{W_{+}(D)}$ and $\tau_{W_{-}(D)}$. They relate to the theta function as follows.

Theorem 13 Let $A$ be the $g \times \infty$-matrix with entries $A_{i j}$ defined by expanding the holomorphic differential forms $\omega_{i}$ in terms of $s$ (around $P$ ), $\omega_{i}=\sum_{j=1}^{\infty} A_{i j} s^{j-1} d s$. Then for any divisor $D$ of degree 0,

$$
\begin{aligned}
\tau_{W_{+}(D)}(t) & =\exp (Q(t)) \theta(\vec{\Delta}-A t-\mathcal{A}(D)), \\
\tau_{W_{-}(D)}(t) & =\exp (Q(t)) \theta(\vec{\Delta}+\vec{e}-A t-\mathcal{A}(D)),
\end{aligned}
$$

where $Q(t)$ is a quadratic form in $t$ which is independent of $t_{1}$.

Proof
The proof is essentially due to Krichever (see [K]), who shows that if L is a line bundle of degree $g$, then

$$
\tau_{W(\mathrm{~L}, \phi)}(t)=\exp (Q(t)) \theta(A t+Z(\mathrm{E})),
$$

for some vector $Z$ which depends "linear" on E in the sense that

$$
\begin{equation*}
Z(\mathrm{E} \otimes[D])=Z(\mathrm{E})+\mathcal{A}(D), \tag{13}
\end{equation*}
$$

for any divisor $D$ of degree 0 (see also [Sh]). We determine $Z$. By the preceding proposition and Theorem $8, \tau_{W_{+}(D)}(0)=0$ iff $l\left(S_{+}(D)\right) \neq 0$ iff $\{D\} \notin J_{0,0}(\Gamma, P)$. On the other hand, by (9) (Riemann's theorem), $\theta(Z)$ vanishes for the points $\mathcal{A}(D)-\vec{\Delta}$ for which $\mathcal{A}(D)=\{D\} \notin J_{0,0}(\Gamma, P)$. Using (13), $Z(\mathrm{E})=\mathcal{A}(D)-\vec{\Delta}$ for all $D$ of degree 0 , leading to the first formula. The second formula follows at once form the first one.

## 4. The master systems

### 4.1. The master systems

Consider for a fixed hyperelliptic curve $\Gamma$ (of genus $g$ ), $P \in \Gamma$ and $s$ a local parameter around $P$ the map

$$
\phi_{P}: \Gamma \rightarrow \operatorname{Jac}(\Gamma): Q \mapsto\{Q-P\} .
$$

Then $d \phi_{P}\left(\frac{\partial}{\partial s}\right)_{s=0}$ is a tangent vector at the origin of $\operatorname{Jac}(\Gamma)$, tangent to the embedded curve $\phi_{P}(\Gamma)$, and we have seen in Proposition 11 that it determines the unique holomorphic vector field on this torus, which coincides with the first K-P vector field, under the identification of $\operatorname{Jac}(\Gamma)$ with $\operatorname{Pic}^{g}(\Gamma)$, given by $\{D\} \leftrightarrow[D+g P]$. Natural coordinates can be picked for (an affine part of) $\operatorname{Jac}(\Gamma)$ in which the differential equations describing the vector field take a nice form. This was done by Mumford in case $P$ is a Weierstraß point on $\Gamma$ (see $[\mathrm{M}]$ ), and by us in the opposite case (see [V]). The result can be written in a compact form as a so-called Lax pair

$$
\frac{d A}{d t}=[A, B], \quad A=\left(\begin{array}{rr}
v(x) & u(x)  \tag{14}\\
w(x) & -v(x)
\end{array}\right), \quad B=\left(\begin{array}{rr}
0 & 1 \\
b & 0
\end{array}\right),
$$

where

$$
u(x)=x^{g}+\sum_{i=1}^{g} u_{i} x^{g-i}, \quad v(x)=\sum_{i=1}^{g} v_{i} x^{g-i}, \quad w(x)=\sum_{i}^{g} w_{i} x^{g-i} .
$$

The sum in $w(x)$ starts from -1 if $P$ is a Weierstraß point and from -2 in the other case; in any case $w(x)$ is taken monic. Moreover, $w_{-1}$ differs from $-u_{1}$ only by a constant, which is normalized to zero by a shift in $x$. With this normalization the entry $b$ in $B$ is given by

$$
b=x-2 u_{1}, \quad \text { or } \quad b=x^{2}-2 u_{1} x+2 u_{1}^{2}-u_{2}+w_{0},
$$

again according to whether $P$ is, or is not, a Weierstraß point of $\Gamma$. In $[\mathrm{V}]$ we called the vector field (14) the odd master system in case $P=P^{\sigma}$ and the even master system otherwise.

The coefficients of $u(x), v(x)$ and $w(x)$ are meromorphic functions on $\operatorname{Jac}(\Gamma)$, which serve as (a complete set of) coordinates for an affine part of $\operatorname{Jac}(\Gamma)$; for example the polynomial $u(x)$ associated to a generic ${ }^{\dagger}$ point $\{D\}=\left\{\sum_{i=1}^{g} P_{i}-g P\right\} \in \operatorname{Jac}(\Gamma)$, is just $u(x)=\prod\left(x-x\left(P_{i}\right)\right)$, hence its coefficients are symmetric functions on the curve; also $v(x)$ is the unique polynomial of degree $g-1$ which records the $y$-values of the points $P_{i}$, i.e., $v\left(x\left(P_{i}\right)\right)=y\left(P_{i}\right)$ for $i=1, \ldots, g$. It follows that $f(x)-v^{2}(x)$ is divisible by $u(x)$ and $w(x)$ is by definition the quotient. Remark that, in particular, an equation for the curve $\Gamma$ is given by

$$
\begin{equation*}
y^{2}=f(x)=u(x) w(x)+v^{2}(x) \tag{15}
\end{equation*}
$$

and the coefficients of $u(x) w(x)+v^{2}(x)$ are constants. Also the points $P$ and $P^{\sigma}$ are points at infinity with respect to this equation. It is easy to deduce from this that the vector field (14) coincides with the vector field given by $d \phi_{P}\left(\frac{\partial}{\partial s}\right)_{\mid s=0}$, hence with the first K-P vector field, as we show now.

Proposition 14 The vector field (14) which describes the master systems coincides with the first $K-P$ vector field $\partial / \partial t_{1}$.

[^1]Proof
Take a generic divisor $P_{1}+\cdots+P_{g}, P_{i}=\left(x_{i}, y_{i}\right)$ and let $u(x), v(x)$ and $w(x)$ be its associated polynomials. Using (14),

$$
y_{i}=v\left(x_{i}\right)=\frac{1}{2} \frac{d u}{d t}\left(x_{i}\right)=-\frac{1}{2} \prod_{j \neq i}\left(x_{i}-x_{j}\right) \frac{d x_{i}}{d t},
$$

hence

$$
\sum_{i=1}^{g} \frac{x_{i}^{k} d x_{i}}{y_{i}}=-2 \sum_{i=1}^{g} \frac{x_{i}^{k} d t}{\prod_{j \neq i}\left(x_{i}-x_{j}\right)}=-2 \delta_{k, g-1} d t .
$$

It follows that the vector field vanishes in the direction of $d x / y, \ldots, x^{g-2} d x / y$ and takes the value -2 for $x^{g-1} d x / y$ exactly as in (12).

### 4.2. The Laurent solutions for the master systems

The differential equations describing a vector field such as (14) are known to possess families of Laurent solutions (see [AvM3]). We explain this by recalling the argument. Let $Z$ be any point on $\operatorname{Jac}(\Gamma)$ and let us denote for simplicity the functions $u_{i}, v_{i}$ and $w_{i}$ by $z_{1}, \ldots, z_{m},(m=$ $3 g+1$ or $m=3 g+2)$. If all functions $z_{i}$ are holomorphic in this point then the solution $z_{i}(t)$ is obviously given by power series; therefore suppose that one or more functions $z_{i}$ blow up at $Z$, say the blow-up locus of $z_{1}$ contains $Z$. We write the divisor of $z_{1}$ as

$$
\left(z_{1}\right)=\sum_{i=1}^{k} n_{i} D_{i}-\sum_{i=1}^{l} m_{i} D_{i}^{\prime} \quad\left(m_{i}, n_{i} \in \mathbb{N} \backslash\{0\}\right),
$$

where all $D_{i}$ and $D_{i}^{\prime}$ are different and irreducible. Then $Z$ belongs to one or more $D_{i}^{\prime}$, but may belong as well to some of the $D_{i}$. In any case, if we pick for each divisor a local defining function around $Z$, say $f_{i}$ for $D_{i}$ and $g_{i}$ for $D_{i}^{\prime}$ (if $Z$ does not belong to some divisor then the local defining function may be taken as the constant function 1 ), then $z_{1}$ is written around $Z$ as

$$
z_{1}=f \frac{f_{1}^{n_{1}} f_{2}^{n_{2}} \cdots f_{k}^{n_{k}}}{g_{1}^{m_{1}} g_{2}^{m_{2}} \cdots g_{l}^{m_{l}}} .
$$

We may take linear coordinates $x_{1}=t, x_{2}, \ldots, x_{n}$ for the torus, and think of the local defining functions as being expressed in terms of these. If the $t$-axis is not contained in any of the divisors $D_{i}$ or $D_{i}^{\prime}$ then all these functions can (again up to a nonvanishing holomorphic function) be written as a (Weierstraß) polynomial in $t$ (by the Weierstraß Preparation Theorem) and we see that the zero or pole $z_{1}$ has in $Z$ depends on the components of the divisor of $z_{1}$ to which $Z$ belongs but also on the singularity these divisors have in $Z$ (since then the first few terms in the series vanish) and on the contact the vector field $d / d t$ has with these divisors (for the same reason). Proceeding in this way for all functions $z_{i}$ we find a Laurent solution to the differential equations, which starts from $Z$. The case in which the $t$-axis is contained in the divisor of one of the functions corresponds to the exceptional case that both the torus is reducible and one of the functions blows up on a subtorus, a case which will not be encountered here.

The Laurent series organize themselves naturally in families as follows: for every $z_{i}$, fix an intersection of some divisors (contained in the divisor of poles of $\left(z_{i}\right)$ ), fix an order of singularity and an order of tangency of the vector field. On this set all $z_{i}$ are written as Laurent series depending on a number of free parameters, equal to the dimension of this set (corresponding to the
starting point of the series which can be chosen in it) and in a dense subset the order of pole each expansion experiences is fixed. The pole may however become less severe in an analytic subset, obtained from the intersection with one of the divisors on which $z_{i}$ has a zero; in such a case the leading coefficient of the Laurent series must be (dependent on) a free parameter, so that it can in particular take the value 0 . The different sets obtained in this way do not give a stratification of the torus in general; indeed, if, for example, $z_{1}$ and $z_{2}$ both have a pole on some smooth divisor and the intersection of these divisors is singular, then this singularity will not be seen by the Laurent series.

Finding all Laurent solutions in a direct way is in general a hard problem. At first it is not clear when looking at the differential equations where to start with the solution. For a given choice one needs to solve a nonlinear system of algebraic equations for the leading term (which may be very difficult, especially in the present case where the number of variables is indefinite; here this number is $3 g+1$ or $3 g+2$ ); the presence of free parameters (giving information about the dimension of the corresponding subset) can in favourable cases be detected by computing the eigenvalues of a matrix, depending on these leading terms, but this is again very difficult when the number of variables, hence the size of the matrix, is indefinite. One also has to show convergence of all Laurent solutions and to see how the different sets they correspond to are related (see [AvM3]).

Our method to find the Laurent solutions for the master systems does not use this scheme. Instead we combine Theorem 12 with the following theorem which expresses the symmetric functions $u_{i}$ in terms of the Riemann theta function. The result is most easily expressed in terms of alternative symmetric functions $U_{i}$ (on the curve, given by (15), defined for a generic point $\{D\}=\left\{\sum_{i=1}^{g} P_{i}-g P\right\} \in \operatorname{Jac}(\Gamma)$, as

$$
U_{i}=U_{i}^{D}=\sum_{j=1}^{g} x^{i}\left(P_{j}\right) \quad(i=1, \ldots, g) .
$$

Remark that $u_{i}$ is a weight homogeneous polynomial in $U_{1}, \ldots, U_{i}$ when $U_{k}$ is given weight $k$. We also introduce the Schur polynomials $p_{i}(x), x=\left(x_{1}, x_{2}, \ldots\right)$ defined by

$$
\exp \left(\sum_{i=1}^{\infty} x_{i} \xi^{i}\right)=\sum_{i=0}^{\infty} p_{i}(x) \xi^{i} .
$$

In order to simplify the notation we will abbreviate

$$
\tilde{\partial}=\left(\frac{\partial}{\partial t_{1}}, \frac{1}{2} \frac{\partial}{\partial t_{2}}, \frac{1}{3} \frac{\partial}{\partial t_{3}}, \ldots\right) .
$$

Theorem 15 If $P=P^{\sigma}$ then the symmetric functions $U_{i}$ are expressed in terms of the Riemann theta function by

$$
\begin{equation*}
U_{i}^{D}=c_{i}-\sum_{j=0}^{2 i-1} \frac{\partial}{\partial t_{2 i-j}} p_{j}(\tilde{\partial})(\log \theta)(\vec{\Delta}-\mathcal{A}(D)) \quad\left(c_{i} \in \mathbb{C}\right) . \tag{16}
\end{equation*}
$$

In particular, since the Schur polynomial $p_{j}(x)$ has degree $j$ in $x_{1}$, the Laurent expansion in $t_{1}$ for $U_{i}$ (and hence also for $u_{i}$ ) will have a leading behaviour which is not worse than $t_{1}^{-2 i}$.

Alternatively, if $P \neq P^{\sigma}$ then the symmetric functions $U_{i}$ are expressed in terms of the Riemann theta function by

$$
\begin{equation*}
U_{i}^{D}=c_{i}-\sum_{j=0}^{i-1} \frac{\partial}{\partial t_{i-j}} p_{j}(\tilde{\partial})(\log \theta)(\vec{\Delta}-\mathcal{A}(D))-\frac{\partial}{\partial t_{i-j}} p_{j}(-\tilde{\partial})(\log \theta)(\vec{\Delta}-\mathcal{A}(D)+\vec{e}) . \tag{17}
\end{equation*}
$$

so that in this case any Laurent expansion in $t_{1}$ for $U_{i}$ (and, hence, also for $u_{n}$ ) will have a leading behaviour which is not worse than $t_{1}^{-i}$.

Proof
The formulas (16) and (17) generalize analogous formulas that have been obtained by several methods for small $n$ (see [D], [MvM]); our proof is a residue calculation as in [D].

The fundamental formula used here is that, if $Z=\mathcal{A}\left(P_{1}+\cdots+P_{g}-g P\right)$ with $P_{1}+\cdots+P_{g}$ a generic divisor on $\Gamma$, then

$$
\theta(\mathcal{A}(Q-P)-Z+\vec{\Delta})=0 \text { iff } Q \in\left\{P_{1}, \ldots, P_{g}\right\}
$$

an easy consequence of (9) (Riemann's Theorem). We start with the case $P=P^{\sigma}$. Then it follows from this formula that $U_{i}^{D}$ is given by

$$
\begin{align*}
U_{i}^{D} & =c_{i}-\operatorname{Res}_{Q=P} x^{i}(Q) d \log \theta(\mathcal{A}(Q-P)-\mathcal{A}(D)+\vec{\Delta}), \\
& =c_{i}-\operatorname{Res}_{Q=P} x^{i}(Q) \sum_{l=1}^{g} \omega_{l}(Q)\left(\frac{\partial}{\partial z_{l}} \log \theta\right)(\mathcal{A}(Q-P)-\mathcal{A}(D)+\vec{\Delta}), \tag{18}
\end{align*}
$$

for some $c_{i} \in \mathbb{C}$. As before, we expand $\omega_{i}$ and the components $\mathcal{A}_{i}$ of the Abel map for $Q$ close to $P$, say $x(Q)=s^{-2}$ in terms of $s$,

$$
\omega_{i}(Q)=\sum_{j=1}^{\infty} A_{i j} s^{j-1} d s \quad \mathcal{A}_{i}(Q)=\sum_{j=1}^{\infty} \frac{1}{j} A_{i j} s^{j} d s
$$

We use Taylor's Theorem,

$$
F(\vec{z}+\vec{h})=\exp \left(\sum_{i=1}^{g} h_{i} \frac{\partial}{\partial z_{i}}\right) F(\vec{z}) \quad(h \text { small })
$$

for

$$
F=\frac{\partial}{\partial z_{l}}(\log \theta), \vec{z}=\vec{\Delta}-\mathcal{A}(D), \vec{h}=\mathcal{A}(Q-P), Q \text { near } P .
$$

This gives

$$
\begin{aligned}
\left(\frac{\partial}{\partial z_{l}} \log \theta\right)(\mathcal{A}(Q-P)-\mathcal{A}(D)+\vec{\Delta}) & =\exp \left[\sum_{j=1}^{\infty}\left(\sum_{i=1}^{g} \frac{1}{j} A_{i j} \frac{\partial}{\partial z_{i}}\right) s^{j}\right]\left(\frac{\partial}{\partial z_{l}} \log \theta\right)(\vec{\Delta}-\mathcal{A}(D)), \\
& =\exp \left[\sum_{j=1}^{\infty} \frac{1}{j} \frac{\partial}{\partial t_{j}} s^{j}\right]\left(\frac{\partial}{\partial z_{l}} \log \theta\right)(\vec{\Delta}-\mathcal{A}(D)), \\
& =\sum_{j=0}^{\infty} s^{j} p_{j}(\tilde{\partial})\left(\frac{\partial}{\partial z_{l}} \log \theta\right)(\vec{\Delta}-\mathcal{A}(D)) .
\end{aligned}
$$

We have used that $\sum_{i=1}^{g} A_{i j} \frac{\partial}{\partial z_{i}}=\frac{\partial}{\partial t_{j}}$, which follows from $z=A t+\zeta$ in Theorem 13. We have now expressed everything in terms of $s$ and can compute the residue:

$$
\begin{aligned}
U_{i}^{D} & =c_{i}-\operatorname{Res} s^{-2 i} \sum_{j=0}^{\infty} p_{j}(\tilde{\partial}) s^{j}\left(\frac{\partial}{\partial z_{l}} \log \theta\right)(\vec{\Delta}-\mathcal{A}(D)) \sum_{k=1}^{\infty} A_{l k} s^{k-1} d s, \\
& =c_{i}-\operatorname{Res} \sum_{j=0}^{\infty} \sum_{k=1}^{\infty} s^{j+k-2 i} p_{j}(\tilde{\partial}) \frac{\partial}{\partial t_{k}}(\log \theta)(\vec{\Delta}-\mathcal{A}(D)) \frac{d s}{s}, \\
& =c_{i}-\sum_{j=0}^{2 i-1} \frac{\partial}{\partial t_{2 i-j}} p_{j}(\tilde{\partial})(\log \theta)(\vec{\Delta}-\mathcal{A}(P)) .
\end{aligned}
$$

The modifications for the case $P \neq P^{\sigma}$ are the following. In (18) there is an extra term corresponding to the residue in $P^{\sigma}$,

$$
\operatorname{Res}_{Q^{\prime}=P} x^{i}\left(Q^{\prime}\right) \sum_{l=1}^{g} \omega_{l}\left(Q^{\prime}\right)\left(\frac{\partial}{\partial z_{l}}(\log \theta)\right)\left(\mathcal{A}\left(Q^{\prime}-P\right)-\mathcal{A}(D)+\vec{\Delta}\right) .
$$

Letting $Q^{\sigma}=Q^{\prime}$ it is rewritten as a residue in $P$ upon using $x\left(Q^{\sigma}\right)=x(Q)$ and $\omega\left(Q^{\sigma}\right)=-\omega(Q)$ for all holomorphic differentials $\omega$ (hence also $\mathcal{A}\left(Q^{\sigma}-P^{\sigma}\right)=-\mathcal{A}(Q-P)$ ), giving:

$$
-\operatorname{Res}_{Q=P} x^{i}(Q) \sum_{l=1}^{g} \omega_{l}(Q)\left(\frac{\partial}{\partial z_{l}} \log \theta\right)(-\mathcal{A}(Q-P)-\mathcal{A}(D)+\vec{\Delta}+\vec{e}) .
$$

A second mayor difference with the case $P=P^{\sigma}$ is that now $x(Q)=s^{-1}$ in terms of the local parameter $s$. Taylor's Theorem gives the same result as above for the residue in $P$, while for the extra residue term we find

$$
\left(\frac{\partial}{\partial z_{l}} \log \theta\right)(-\mathcal{A}(Q-P)-\mathcal{A}(D)+\vec{\Delta}+\vec{e})=\sum_{j=0}^{\infty} s^{j} p_{j}(-\tilde{\partial})\left(\frac{\partial}{\partial z_{l}} \log \theta\right)(\vec{\Delta}+\vec{e}-\mathcal{A}(D)),
$$

so that finally the sum of the two residue terms is given by

$$
\begin{aligned}
& -\operatorname{Res} \sum_{j=0}^{\infty} \sum_{k=1}^{\infty} s^{j+k-i}\left(\frac{\partial}{\partial t_{k}} p_{j}(\tilde{\partial})(\log \theta)(\vec{\Delta}-\mathcal{A}(D))-\frac{\partial}{\partial t_{k}} p_{j}(-\tilde{\partial})(\log \theta)(\vec{\Delta}+\vec{e}-\mathcal{A}(D))\right) \frac{d s}{s}, \\
& =c_{i}-\sum_{j=0}^{i-1}\left(\frac{\partial}{\partial t_{i-j}} p_{j}(\tilde{\partial})(\log \theta)(\vec{\Delta}-\mathcal{A}(D))-\frac{\partial}{\partial t_{i-j}} p_{j}(-\tilde{\partial})(\log \theta)(\vec{\Delta}+\vec{e}-\mathcal{A}(D))\right) .
\end{aligned}
$$

The above theorem is very helpful to determine the Laurent solutions for the master systems. Since $t=t_{1}$, we may now make the ansatz

$$
\begin{equation*}
u_{i}=\frac{1}{t^{\rho(i)}} \sum_{j=1}^{\infty} u_{i j} t^{j} \tag{19}
\end{equation*}
$$

where $\rho(i)$ is given by the theorem, namely $\rho(i)=2 i$ if $P=P^{\sigma}$ and $\rho(i)=i$ otherwise, and we are sure to find all the Laurent solutions. We show that they lead indeed to the stratification of $\mathrm{Jac}(\Gamma)$ which coincides with the one by the subsets $J_{m, n}(\Gamma, P)$. We give separate propositions for the cases $P=P^{\sigma}$ and $P \neq P^{\sigma}$.

Proposition 16 For the odd master system there are $g+1$ families of Laurent solutions. The mth family corresponds to the stratum $J_{m}(\Gamma, P)$ and the functions $u_{1}, \ldots, u_{g}$ blow up as

$$
\begin{array}{lr}
u_{i}=(-1)^{i} \frac{(2 i-1)!!}{2^{i} i!} \frac{(m+i)!}{(m-i)!} \frac{1}{t^{2 i}}+\mathcal{O}\left(t^{-2 i+1}\right) & (i=1, \ldots, m),  \tag{20}\\
u_{i}=\mathcal{O}\left(t^{-2 i+1}\right) & (i=m+1, \ldots, g),
\end{array}
$$

In particular, the odd master system induces a stratification on $\operatorname{Jac}(\Gamma)$ which coincides with the stratification by the subsets $J_{m}(\Gamma, P)$.

Proof
Equations (14) are written out in the case of the odd master system (corresponding to $P=P^{\sigma}$ ) as

$$
\begin{aligned}
\dot{u}(x) & =2 v(x), \\
\dot{v}(x) & =-w(x)+\left(x-2 u_{1}\right) u(x), \\
\dot{w}(x) & =-2\left(x-2 u_{1}\right) v(x),
\end{aligned}
$$

or just as a third order equation,

$$
\begin{equation*}
\dddot{u}_{i}(x)=4\left(\dot{u}_{i+1}-2 u_{1} \dot{u}_{i}-\dot{u}_{1} u_{i}\right) \quad\left(i=1, \ldots, g ; u_{g+1}=0\right) . \tag{21}
\end{equation*}
$$

Then the ansatz (19) leads to the recursion relation

$$
\begin{equation*}
a_{i+1}=\frac{2 i+1}{i+1}\left[\frac{i(i+1)}{2}+a_{1}\right] a_{i} . \tag{22}
\end{equation*}
$$

To solve this recursion relation, remark that if $a_{i}=0$ then $a_{i+1}=0$; since $a_{i}=0$ for at least one $i \leq g+1$, we find that

$$
\begin{equation*}
a_{1}=-\frac{1}{2} m(m+1) \tag{23}
\end{equation*}
$$

for some $m \in\{0, \ldots, g\}$ which leads by induction immediately to the formula

$$
a_{i}=(-1)^{i} \frac{(2 i-1)!!}{2^{i} i!} \frac{(m+i)!}{(m-i)!} \quad(i=1, \ldots, m),
$$

and $a_{m+1}=\cdots=a_{g}=0$, hence also to (20). The series for $v_{i}$ and $w_{i}$ follow immediately from it by differentiation, in particular they do not give rise to separate families of Laurent solutions.

We now show that the $m$ th solution corresponds to $J_{m}(\Gamma, P)$. Take $\{D\} \in J_{m}(\Gamma, P)$ and let $\left\{D^{t}\right\}$ be the integral curve of $d / d t=\partial / \partial t_{1}$ with $D^{0}=D$. Denote by $u^{D^{t}}(x)$ and $U^{D^{t}}(x)$ the
associated polynomials, as above. Since it follows from the definition of $A$ that $A t+\mathcal{A}(D)=\mathcal{A}\left(D^{t}\right)$, we may compute, using Theorems 15, 13 and Proposition 12 (in that order),

$$
\begin{aligned}
u_{1}^{D^{t}} & =(\log \theta) \cdot \cdot\left(\vec{\Delta}-\mathcal{A}\left(D^{t}\right)\right)-c_{1}, \\
& =(\log \theta) \cdot \cdot(\vec{\Delta}-\mathcal{A}(D)-A t)-c_{1}, \\
& =\left(\log \tau_{W_{+}(D)}\right) \cdot(t)-c_{1}, \\
& =\frac{d^{2}}{d t^{2}} \log \left(c t^{l\left(S_{+}(D)\right)}+\mathcal{O}\left(t^{l\left(S_{+}(D)\right)+1}\right)\right)-c_{1}, \quad(c \neq 0), \\
& =-\frac{l\left(S_{+}(D)\right)}{t^{2}}+\mathcal{O}(1) .
\end{aligned}
$$

If $\{D\} \in J_{m}(\Gamma, P)$, then we know from Theorem 8 that $l\left(S_{+}(D)\right)=\frac{m(m+1)}{2}$, so we find by (23) that the $m$ th stratum corresponds to $J_{m}$.

We will now formulate and prove the corresponding result for the even master system, i.e., for the case $P \neq P^{\sigma}$.

Proposition 17 For the even master system there are $\frac{(g+1)(g+2)}{2}$ families of Laurent solutions one for each element of the set $\mathcal{I}_{g}$. The $(m, n)$ th family corresponds to the stratum $J_{m, n}(\Gamma, P)$ and the functions $u_{1}, \ldots, u_{g}$ blow up as

$$
\begin{align*}
& u_{1}=\frac{m-n}{t}+\mathcal{O}(1),  \tag{24}\\
& u_{i}=\mathcal{O}\left(t^{-i}\right),
\end{align*} \quad(i=m+1, \ldots, g),
$$

In particular, the even master system induces a stratification on $\operatorname{Jac}(\Gamma)$ which coincides with the stratification by the subsets $J_{m, n}(\Gamma, P)$.

Proof
The proof goes along the same lines as the proof of Proposition 16. However one finds using the ansatz in this case a recursion relation

$$
a_{k+2}=\frac{2 k+3}{k+2} a_{1} a_{k+1}+\frac{k+1}{k+2}\left[(k+2) k-\left(3 a_{1}^{2}-2 a_{2}\right)\right] a_{k},
$$

which is solved at once for $g=1,2,3, \ldots$, but seems to be very hard to solve for general $g$. Therefore we compute as in the previous proposition for $\{D\} \in J_{m, n}(\Gamma, P)(\Gamma, P)$ with $(m, n) \in \mathcal{I}_{g}$ :

$$
\begin{aligned}
u_{1}^{D^{t}} & =(\log \theta) \cdot\left(\vec{\Delta}-\mathcal{A}\left(D^{t}\right)\right)-(\log \theta) \cdot\left(\vec{\Delta}-\mathcal{A}\left(D^{t}\right)+\vec{e}\right)-c_{1}, \\
& =\left(\log \tau_{W_{+}(D)}\right) \cdot(t)-\left(\log \tau_{W_{-}(D)}\right)^{\cdot}(t)-c_{1}, \\
& =\frac{l\left(S_{+}(D)\right)-l\left(S_{-}(D)\right)}{t}+\mathcal{O}(1), \\
& =\frac{m-n}{t}+\mathcal{O}(1) .
\end{aligned}
$$

The formula for the other $u_{i}$ follows from Theorem 15.

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[^0]:    ${ }^{\dagger}$ by the last condition in (10) we singled out the connected component containing $\mathcal{H}_{+}$of what [PS] and [SS] call the Grassmannian

[^1]:    ${ }^{\dagger}$ generic means here that the point lies in $J_{0,0}(\Gamma, P)$

