# Qualitative Properties of Eigenvectors Related to Multivalued Operators and some Existence Results 

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#### Abstract

In this work, we study a class of nonlinear eigenvalue problems related to fully discontinuous operators. In particular, we prove the existence of a critical point for two distinct problems. Connected with this problem, we also study a minimization problem with constraint and we investigate the existence of solutions for a resonant case near zero. Moreover, we give some estimates and qualitative properties of solutions by using the relative rearrangement theory.


Keywords Nonlinear eigenvalues • Multivalued operators • Clarke subdifferential • Relative rearrangement • Monotone rearrangement

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## 1 Introduction.

Eigenvalue problems involving nonhomogeneous elliptic operators have captured special attention in the last decade. Numerous papers have been devoted to the study of various phenomena, which occur in the spectrum of such operators (see $1-7$ and references therein). The purpose of the present paper is to give additional results on eigenvalue problems related to fully discontinuous operators, which recover the results in [1,2]; indeed, the operator given here,

[^0]which is recently introduced by J.M. Rakotoson, becomes a natural extension of the univalued operator studied recently in 2 .

## 2 Presentation of the Problem.

The study of this issue was initiated by J.M. Rakotoson in [8], in which the notion of $\vec{\rho}$-multivalued Leray-Lions operators was introduced by

$$
\begin{equation*}
-\operatorname{div}_{\vec{\rho}}\left(\partial \varphi_{i}\left(x, \frac{\partial u}{\partial x_{i}}(x)\right)\right) \tag{1}
\end{equation*}
$$

associated to $\vec{\rho}=\left(\rho_{0}, \ldots, \rho_{N}\right)$, where $\rho_{i}$ are Banach function norms and $\varphi_{i}$ are Carathéodory functions on $\Omega \times \mathbb{R}$, such that, for a.e. $t \mapsto \varphi_{i}(x, t)$ is locally Lipschitz on $\mathbb{R}$; therefore the theoretical formulation of such concrete problems basically relies on the notion of Clarke's generalized gradient, which replaces the subdifferential in the sense of convex analysis (see 9$]$ ).
This operator can be used in the Euler-Lagrange functionals, that appear in the minimization problems of image restoration (see [10]).

In this paper, we shall consider the same Orlicz-Sobolev spaces used in 11 (see also $|12|$ ), that will enable us to study with sufficient accuracy problem (2). For this purpose, we consider as Banach function norm:

$$
\rho(v):=\inf \left\{\lambda>0: \int_{\Omega} \varphi\left(x, \frac{|v(x)|}{\lambda}\right) \mathrm{d} x \leqslant 1\right\}
$$

where $\varphi$ is a suitable $N$-function (see $[13]$ ), and $L(\Omega, \rho)$ is the associated Banach function space.
Moreover, we shall give additional results concerning the resolution of the eigenvalue problem

$$
\begin{equation*}
-\operatorname{div}_{\vec{\rho}}\left(\partial \varphi_{i}\left(x, \frac{\partial u}{\partial x_{i}}(x)\right)\right)=\lambda f(x, u(x)), \quad f(x, u(x)) \in \partial j_{0}(x, u(x)) \tag{2}
\end{equation*}
$$

under some assumptions on the function $j_{0}$, assumptions that place us in a different context from the one studied in 11. Let us note that existence results are deeply influenced by the competition between the growth rates of the anisotropic coefficients.
The results presented here extend previous works of M. Mihăilescu and al. in 1, 2. We define on $W_{0}^{1, p}(\Omega)$ the functionals $J$ and $j$, such that, for all $v \in W_{0}^{1, p}(\Omega)$,

$$
\begin{gathered}
J(v):=\frac{1}{p} \sum_{i=1}^{N}\left[\int_{\left\{\left|\frac{\partial v}{\partial x_{i}}\right| \leqslant 1\right\}}\left|\frac{\partial v}{\partial x_{i}}\right|^{q} \mathrm{~d} x+\int_{\left\{\left|\frac{\partial v}{\partial x_{i}}\right|>1\right\}}\left|\frac{\partial v}{\partial x_{i}}\right|^{p} \mathrm{~d} x\right], \\
j_{0}(v):=\frac{1}{p_{M}}\left[\int_{\{|v| \leqslant 1\}}|v|^{q_{M}} \mathrm{~d} x+\int_{\{|v|>1\}}|v|^{p_{M}} \mathrm{~d} x\right] .
\end{gathered}
$$

Then, for all $\lambda \in] 0, \lambda_{*}\left[\right.$, there exists a function $u \geqslant 0, u \not \equiv 0, u \in W_{0}^{1, p}(\Omega)$ such that $0 \in \partial J(u)-\lambda \partial j_{0}(u)$, provided
$1<q<p<+\infty, 1<q_{M}<p_{M}<p^{*}=\frac{N p}{N-p}$ and $q_{M}<q$.
Moreover, for all $\lambda>\lambda_{* *}$, there exists a non-trivial solution $u \in W_{0}^{1, p}(\Omega)$ such that $0 \in \partial J(u)-\lambda \partial j_{0}(u)$, provided
$1<q<p<+\infty, 1<q_{M}<p_{M}<p^{*}$ and $p_{M}<q$.
In order to go further, we will exploit the nonsmooth version of the Lagrange multiplier theorem (see $[9]$ ) to prove the existence of solutions for a more general problem. Moreover, this existence result will be used in the last section, in which we are able to characterize and prove the $L^{\infty}$-regularity of the eigenvectors associated to $\vec{\rho}$-multivalued Leray-Lions operators by using the relative rearrangement theory (see [14]).
To our knowledge, this is the first paper dealing with the regularity of the eigenvectors related to $\vec{\rho}$-multivalued Leray-Lions operators.

We also obtain an existence result for an eigenvalue problem in a resonant case near zero in the sense that the potential has the same growth as the operator in a small neighborhood of the origin.
Our result shall recover the following problem. Consider $J$ as above and

$$
h(x, \sigma):= \begin{cases}\frac{c^{*}}{p}|\sigma|^{p} & \text { if }|\sigma|<1 \\ \frac{1}{\beta}|\sigma|^{\beta}-|\sigma|+\frac{c^{*}}{p}+\frac{\beta-1}{\beta} & \text { otherwise }\end{cases}
$$

where $0<c^{*}<\frac{1}{N^{p} \cdot S^{p}}$, the positive constant $S$ is the Sobolev embedding constant of $W_{0}^{1, p}(\Omega)$ into $L^{p}(\Omega)$ and $p<\beta<p^{*}$. Then, there exists a nontrivial solution $u \in W_{0}^{1, p}(\Omega)$ such that $0 \in \partial J(u)-\partial j(u)$ and $j(u)=\int_{\Omega} h(x, u(x)) \mathrm{d} x$.

We start by recalling some basic facts about Clarke subdifferential, Banach function norms, $\vec{\rho}$-multivalued operators, Orlicz spaces and relative rearrangement. For more details we refer to $[8,9,11,13,18]$.

## 3 Notations - Preliminary Results.

For a Banach space $(V,\|\cdot\|)$, we shall denote by $V^{\prime}$ its dual, and the duality bracket between $V^{\prime}$ and $V$ shall be denoted by $\langle\cdot, \cdot\rangle$. The set of all subsets of $V^{\prime}$ is denoted by $\mathcal{P}\left(V^{\prime}\right):=2^{V^{\prime}}$. In order to avoid confusion, we shall also denote by $\|\cdot\|_{V}$ or $\|\cdot\|_{V^{\prime}}$ the norms in those spaces.

Definition 3.1 The first statement of the definition is already known (see [19]), the second one was introduced recently in [8].

1. A multivalued operator $A: V \rightrightarrows \mathcal{P}\left(V^{\prime}\right)$ is called a monotone operator iff: $\forall u_{1}, u_{2} \in V, \forall w_{1} \in A u_{1}, \forall w_{2} \in A u_{2}$, we have $<w_{1}-w_{2}, u_{1}-u_{2}>\geqslant 0$.
2. A multivalued monotone operator $A$ is strongly monotonic iff for any sequence $\left(u_{n}\right)_{n}$ in $V$ converging weakly to a function $u$ and verifying:
$\forall w_{n} \in A u_{n}, \forall w \in A u$ if $\lim _{n \rightarrow+\infty}<w_{n}-w, u_{n}-u>=0$, then $u_{n}$ converges to $u$ strongly in $V$.

Definition 3.2 20 22 .

1. We call $j: V \rightarrow \mathbb{R}$ to be a locally Lipschitz function iff for all $u \in V$, there exist a ball $B(u, r), r>0$ and a constant $K_{r}(u)=K(u)$ such that

$$
|j(v)-j(w)| \leqslant K(u)\|v-w\|, \quad \forall v, w \in B(u, r)
$$

2. For each $v \in V$, the generalized directional derivative of $j$ (at a point $u$ in the direction $v$ ), denoted by $j^{0}(u ; v)$, is defined as follows:

$$
j^{0}(u ; v):=\limsup _{\lambda \searrow 0, h \rightarrow 0} \frac{j(u+h+\lambda v)-j(u+h)}{\lambda} .
$$

On the basic properties of the generalized directional derivative we refer to 9.2022.

Definition $3.3 \quad 20-22$. The (Clarke) subdifferential of $j$ at a point $u \in V$ is the subdifferential of the convex map $v \mapsto j^{0}(u ; v)$ at zero. More precisely,

$$
\partial j(u):=\left\{w \in V^{\prime}:<w, v>\leqslant j^{0}(u ; v), \forall v \in V\right\} .
$$

For these reasons, the Clarke subdifferential possesses the same properties as the subdifferential in the sense of convex analysis. For more information on these properties we refer to $[9,20,22$.

Definition $3.420-22$.
If $j: V \rightarrow \mathbb{R}$ is a locally Lipschitz function, we say that $u$ is a critical point of $j$ iff $0 \in \partial j(u)$.

We shall use the following notions on Banach function norms and spaces (see [15] and also 14 for more details). Let $L^{0}(\Omega):=\{v: \Omega \rightarrow \mathbb{R}$ Lebesgue measurable $\}$
and $L_{+}^{0}(\Omega):=\left\{v \in L^{0}(\Omega), v \geqslant 0\right\}$.
Definition 3.5 15]. A mapping $\rho: L_{+}^{0}(\Omega) \rightarrow \overline{\mathbb{R}}_{+}:=[0,+\infty]$ is called a Banach function norm iff, for all $f, g$ and $g_{n}$ in $L_{+}^{0}(\Omega)$, for all measurable set $E \subset \Omega$, we have
P1./ $\rho(f)=0 \Longleftrightarrow f=0$ a.e.,
$\rho(\lambda f)=\lambda \rho(f), \quad \forall \lambda>0$,
$\rho(f+g) \leqslant \rho(f)+\rho(g)$.
P2./ If $f \leqslant g$ a.e. then $\rho(f) \leqslant \rho(g)$.

P3./ If $f_{n} \leqslant f_{n+1} \nearrow f$ then $\rho\left(f_{n}\right) \rightarrow \rho(f)$.
P4./ If $|E|<+\infty$ then $\rho\left(\chi_{E}\right)<+\infty$. ( $|E|$ is the Lebesgue measure of $E$ and $\chi_{E}$ is the characteristic function of $\left.E\right)$.
P5./ If $|E|<+\infty$ then $\int_{E} f(x) \mathrm{d} x \leqslant c_{E} \rho(f)$ for some finite, positive constant $c_{E}$ depending only on $E$ and $\rho$.

Definition 3.6 15. Let $\rho$ be a Banach function norm. Then, we define

$$
Y:=L(\Omega, \rho)=\left\{f \in L^{0}(\Omega): \rho(|f|)<+\infty\right\}
$$

$Y$ is called a Banach function space and is endowed with the norm $\|f\|_{Y}=\rho(|f|)$.

In what follows we state some useful properties of $L(\Omega, \rho)$ :
Definition 3.7 15.

1. If $\rho$ is a Banach function norm, its associate norm $\rho^{\prime}$ is defined by

$$
\rho^{\prime}(f):=\sup \left\{\int_{\Omega} f g \mathrm{~d} x, g \in L_{+}^{0}(\Omega), \rho(g) \leqslant 1\right\}, \text { for } f \in L_{+}^{0}(\Omega)
$$

2. The Banach function space determined by $\rho^{\prime}$ is called the associate Banach function space of $L(\Omega, \rho)$, that is $L\left(\Omega, \rho^{\prime}\right):=\left\{v \in L^{0}(\Omega): \rho^{\prime}(|v|)<+\infty\right\}$.

Definition 3.8 15.
A Banach function space $Y$ is said to have absolutely continuous norm iff

$$
\left\|f \chi_{E_{n}}\right\|_{Y} \rightarrow 0, \text { for every }\left\{E_{n}\right\} \text { satisfying } E_{n+1} \subset E_{n} \text { and } \quad\left|E_{n}\right| \rightarrow 0
$$

Theorem 3.1 15. A Banach function space $Y$ is reflexive if and only if both $Y$ and its associate $Y^{\prime}$ have absolutely continuous norm.

Remark 3.1 For simplicity, we sometimes write $\rho(f)=\rho(|f|)$, and various constants depending on data shall be denoted by $c$ or $c_{i}$.
The following definitions and results were introduced in [8, 11] (see also [23]). Let $(V,\|\cdot\|)$ and $(X,|\cdot|)$ be two reflexive Banach spaces.

Lemma 3.1 8. Consider two locally Lipschitz functions $J: V \rightarrow \mathbb{R}$ and $j: X \rightarrow \mathbb{R}$. We suppose that
H1./ $\begin{aligned} A: V & \rightrightarrows \mathcal{P}\left(V^{\prime}\right) \\ u & \mapsto \partial J(u)\end{aligned}$ be strongly monotonic.
H2./ We have the following growth:

1. $\exists \beta>0, \exists c_{0} \geqslant 0: \quad \beta j(u) \leqslant \inf _{v^{*} \in \partial j(u)}<v^{*}, u>+c_{0} \beta, \quad \forall u \in X$.
2. There are constants $c_{1}>0, c_{2} \geqslant 0$ :

$$
\frac{1}{\beta} \sup _{w^{*} \in \partial J(u)}<w^{*}, u>-c_{2}+c_{1}\|u\| \leqslant J(u), \quad \forall u \in V
$$

Under these hypotheses and assuming that the injection of $V$ into $X$ be compact, the function $\Phi(u):=J(u)-j(u), u \in V$ satisfies the Palais-Smale conditions.

Definition 3.9 8. Let $\Omega$ be an open set of $\mathbb{R}^{N}$ and $\rho_{0}, \ldots, \rho_{N}$ be $(N+1)$ Banach function norms and $L\left(\Omega, \rho_{i}\right), i=0, \ldots, N$ the corresponding Banach function space. We define the following Banach-Sobolev function space

$$
\begin{aligned}
\mathbf{W} & :=W^{1, \rho_{0}, \ldots, \rho_{N}}(\Omega) \\
& :=\left\{v \in L\left(\Omega, \rho_{0}\right), \frac{\partial v}{\partial x_{i}} \in L\left(\Omega, \rho_{i}\right), i=1, \ldots, N\right\} .
\end{aligned}
$$

The norm on $\mathbf{W}$ is then $\|v\|_{\mathbf{W}}=\sum_{i=1}^{N} \rho_{i}\left(\frac{\partial v}{\partial x_{i}}\right)+\rho_{0}(v)$.
Proposition 3.1 8. Let $\rho_{0}, \ldots, \rho_{N}$ be $(N+1)$ Banach function norms, $\rho_{i}^{\prime}$ is the associate norm of $\rho_{i}$. We assume that $\rho_{i}$ and $\rho_{i}^{\prime}$ be absolutely continuous norms. Then, the dual space $\mathbf{V}^{\prime}:=\left(W_{0}^{1, \rho_{0}, \ldots, \rho_{N}}(\Omega)\right)^{\prime}$ is

$$
\begin{aligned}
\mathbf{V}^{\prime}= & \left\{T: \text { there exist } f_{0}, \ldots, f_{N} \text { such that } f_{i} \in L\left(\Omega, \rho_{i}^{\prime}\right)\right. \text { and } \\
& \left.<T, v>:=\int_{\Omega} v(x) f_{0}(x) \mathrm{d} x+\sum_{i=1}^{N} \int_{\Omega} f_{i}(x) \frac{\partial v}{\partial x_{i}}(x) \mathrm{d} x, \forall v \in \mathbf{V}\right\} .
\end{aligned}
$$

Definition 3.10 [8]. We define the $\vec{\rho}$-multivalued Leray-Lions operator as follows:

$$
-\operatorname{div}_{\vec{\rho}}\left(\partial \varphi_{i}\left(x, \frac{\partial u}{\partial x_{i}}(x)\right)\right):=-\sum_{i=1}^{N} \frac{\partial w_{i}}{\partial x_{i}}(x)+\omega_{0}(x) \quad \text { in } \mathcal{D}^{\prime}(\Omega)
$$

Here, $\vec{\rho}$ stands for $\left(\rho_{0}, \ldots, \rho_{N}\right)$ with $w_{0}(x) \in \partial \varphi_{0}(x, u(x))$ a.e. in $\Omega$, and

$$
w_{i}(x) \in \partial \varphi_{i}\left(x, \frac{\partial u}{\partial x_{i}}(x)\right) \text { a.e. in } \Omega, \text { for } i=1, \ldots, N .
$$

## Lemma 3.2 (Construction of a $\vec{\rho}$-multivalued Leray-Lions Strongly

 Monotonic Operator) 11].Let $\Omega$ be a bounded Lipschitz open set of $\mathbb{R}^{N}$ and consider $N$ borelian functions $\phi_{i}: \Omega \times \mathbb{R} \rightarrow \mathbb{R}, i=1, \ldots, N$, such that
A.1/ For a.e. $x \in \Omega$, the $\operatorname{map} t \xrightarrow{\phi_{i}(x, \cdot)} \phi_{i}(x, t)$ is strictly increasing, odd and $\phi_{i}(x, 0)=0$. Moreover, $\phi_{i}(x, \cdot)$ is right continuous on $[0,+\infty[$ and $\lim _{t \rightarrow+\infty} \operatorname{essinf} \phi_{\Omega}(x, t)=+\infty$.
A2./ There exist $2 m$-numbers, $a_{1}<\ldots<a_{2 m}$ such that for a.e. $x \in \Omega, t \in \mathbb{R} \backslash\left\{a_{1}, \ldots, a_{2 m}\right\} \mapsto \phi_{i}(x, t)$ is continuous.

We define on $\Omega \times \mathbb{R}$ the following $N$-function (see 11,13 )

$$
\varphi_{i}(x, t):=\int_{0}^{|t|} \phi_{i}(x, \sigma) \mathrm{d} \sigma
$$

We need that $\varphi_{i}(x, \cdot)$ satisfies the so-called global $\Delta_{2}$-condition (or near infinity). Following the necessary and sufficient condition given in 13,24 , we shall assume
A3./ There exist two numbers $\underline{\alpha}>1, \bar{\alpha}>1$ such that, for a.e. $x, \forall t \in \mathbb{R}$

$$
\underline{\alpha} \varphi_{i}(x, t) \leqslant t w_{i}(x, t) \leqslant \bar{\alpha} \varphi_{i}(x, t), \quad \forall w_{i}(x, t) \in \partial \varphi_{i}(x, t)
$$

As usual, we define the corresponding Orlicz space by considering

$$
L^{\varphi_{i}}(\Omega):=\left\{v: \Omega \rightarrow \mathbb{R} \text { measurable : } \int_{\Omega} \varphi_{i}(x, v(x)) \mathrm{d} x<+\infty\right\}
$$

we endowed this space with the Banach function norm

$$
\begin{equation*}
\rho_{i}(v):=\inf \left\{\lambda>0: \int_{\Omega} \varphi_{i}\left(x, \frac{v(x)}{\lambda}\right) \mathrm{d} x \leqslant 1\right\} \tag{3}
\end{equation*}
$$

We also assume that the conjugate function

$$
\widetilde{\varphi}_{i}(x, \cdot):=\sup _{s \geqslant 0}\left\{t s-\varphi_{i}(x, s)\right\}, \text { for } t \geqslant 0
$$

satisfies the $\Delta_{2}$-condition globally (or near infinity), say that there exists a constant $k>0$, such that $\widetilde{\varphi}_{i}(x, 2 t) \leqslant k \widetilde{\varphi}_{i}(x, t)$ a.e., $\forall t \geqslant 0$ (or $\left.t \geqslant t_{0}\right)$.

Remark 3.2 23. 25. Assume that $\varphi_{i}(x, \cdot)$ satisfy the $\Delta_{2}$-condition globally (or near infinity) and for a.e. the function $t \in\left[0,+\infty\left[\mapsto \varphi_{i}(x, \sqrt{t})\right.\right.$ be convex. Then $\widetilde{\varphi}_{i}(x, \cdot)$ satisfies the $\Delta_{2}$-condition globally (or near infinity).

The Orlicz-Sobolev space associated to $\vec{\rho}=\left(\rho_{1}, \ldots, \rho_{N}\right)$ is
$W_{0}^{1, \rho_{1}, \ldots, \rho_{N}}(\Omega):=\left\{v \in L^{1}(\Omega): \frac{\partial v}{\partial x_{i}}(x) \in L\left(\Omega, \rho_{i}\right), i=1, \ldots, N, \gamma_{0} v=0\right\}$.
We define the function $J(v):=\sum_{i=1}^{N} \int_{\Omega} \varphi_{i}\left(x, \frac{\partial v}{\partial x_{i}}(x)\right) \mathrm{d} x$.
Theorem 3.2 11. Assume A1./, A2./, A3./. Then, the $\vec{\rho}$-multivalued Leray-Lions operator defined by $A u:=-\operatorname{div}{ }_{\rho}\left(\partial \varphi_{i}\left(x, \frac{\partial u}{\partial x_{i}}(x)\right)\right)$ is strongly monotonic on the Orlicz-Sobolev space $\mathbf{V}_{0}:=W_{0}^{1, \rho_{1}, \ldots, \rho_{N}}(\Omega)$.
Remark 3.3 11,23. The following properties hold:

1. $W_{0}^{1, \rho_{1}, \ldots, \rho_{N}}(\Omega) \subset W_{0}^{1,1}(\Omega)$ is a continuous injection.
2. One has for all $t>0$, all $\sigma>1$,

$$
\sigma^{\underline{\alpha}} \varphi_{i}(x, t) \leqslant \varphi_{i}(x, \sigma t) \leqslant \sigma^{\bar{\alpha}} \varphi_{i}(x, t), \text { for a.e. } x \in \Omega .
$$

3. Moreover, we have $L^{\bar{\alpha}}(\Omega) \subset L^{\varphi_{i}}(\Omega) \subset L^{\underline{\alpha}}(\Omega)$ (see [16, 23]).

The next definitions and results can be found in 14 .
Let $\Omega$ be a bounded domain in $\mathbb{R}^{N}$ and $u: \Omega \rightarrow \overline{\mathbb{R}}$ be a measurable function on $\Omega$.
Definition 3.11 We define the function $\left.u_{*}: \Omega_{*}:=\right] 0,|\Omega|[\rightarrow \mathbb{R}$ by setting

$$
u_{*}(s):=\inf \{t \in \mathbb{R}:|u>t| \leqslant s\} \quad s \in \Omega_{*},
$$

and $u_{*}(0):=\underset{\Omega}{\operatorname{esssup}} u, u_{*}(|\Omega|):=\underset{\Omega}{\operatorname{essinf}} u$. The function $u_{*}$ is called the decreasing rearrangement of $u$.
Property 3.1 , 14 . The decreasing rearrangement of $u$ satisfies:

1. $\|u\|_{L^{p}(\Omega)}=\left\|u_{*}\right\|_{L^{p}\left(\Omega_{*}\right)}, \quad$ for $1 \leqslant p \leqslant+\infty$.
2. $\left(|u|^{p}\right)_{*}=\left(|u|_{*}\right)^{p}$ a.e., for $1 \leqslant p<+\infty$.

Theorem 3.314 . Let $u, v \in L^{1}(\Omega)$ and $w: \overline{\Omega_{*}} \longrightarrow \mathbb{R}$ defined by

$$
w(s):=\int_{\left\{u>u_{*}(s)\right\}} v(x) \mathrm{d} x+\int_{0}^{s-\left|u>u_{*}(s)\right|}\left(\left.v\right|_{\left\{u=u_{*}(s)\right\}}\right)_{*}(\sigma) d \sigma,
$$

where $\left.v\right|_{\left\{u=u_{*}(s)\right\}}$ is the restriction of $v$ to $\left\{u=u_{*}(s)\right\}$.
If $v \in L^{p}(\Omega), 1 \leqslant p \leqslant+\infty$, then

1. $w \in W^{1, p}\left(\Omega_{*}\right)$.
2. $\frac{(u+\lambda v)_{*}-u_{*}}{\lambda} \rightharpoonup_{\lambda \rightarrow 0} \frac{d w}{d s} \begin{cases}\text { in } L^{p}\left(\Omega_{*}\right)-\text { weak, } & \text { if } 1 \leqslant p<+\infty, \\ \text { in } L^{\infty}\left(\Omega_{*}\right)-\text { weak- } & \text { if } p=+\infty .\end{cases}$

Definition 3.12 The function $\frac{d w}{d s} \in L^{p}\left(\Omega_{*}\right)$ is called the relative rearrangement of $v$ with respect to $u$ and is denoted by $v_{* u}:=\frac{d w}{d s}$.
Property 3.214 . Let $u \in L^{1}(\Omega)$ and $v \in L^{p}(\Omega), 1 \leqslant p \leqslant+\infty$, the relative rearrangement $v_{* u}$ verifies:

1. $\left\|v_{* u}\right\|_{L^{p}\left(\Omega_{*}\right)} \leqslant\|v\|_{L^{p}(\Omega)}$.
2. $\int_{\Omega_{*}} v_{* u}(s) d s=\int_{\Omega} v(x) \mathrm{d} x$.
3. If $v_{1} \leqslant v_{2}$ a.e., $v_{i} \in L^{p}(\Omega)$, then $v_{1 * u} \leqslant v_{2 * u}$ a.e.
4. If $\alpha>0$, then $(\alpha v)_{* u}=\alpha v_{* u}$.

Theorem 3.4 Poincaré-Sobolev Inequality for the Relative Rearrangement, see 14], Theorem 4.1.1. Let $u \in W_{0}^{1,1}(\Omega), u \geqslant 0$.
Then, $u_{*} \in W_{\text {loc }}^{1,1}\left(\Omega_{*}\right)$ and

$$
\begin{equation*}
-u_{*}^{\prime}(s) \leqslant \frac{s^{\frac{1}{N}-1}}{N \omega_{N}^{\frac{1}{N}}}|\nabla u|_{* u}(s), \quad \text { a.e. in } \Omega_{*} . \tag{4}
\end{equation*}
$$

Lemma 3.3 14. Let $1 \leqslant p \leqslant+\infty, v \in L^{p}(\Omega)$ such that $v_{*} \in W_{l o c}^{1,1}\left(\Omega_{*}\right)$, then $\forall g \in L^{p^{\prime}}(\Omega), G(s)=\int_{\Omega} g \cdot\left(v-v_{*}(s)\right)_{+} \mathrm{d} x \in W_{l o c}^{1,1}\left(\Omega_{*}\right)$, and for a.e. $s \in \Omega_{*}$, we have:

$$
\begin{equation*}
G^{\prime}(s)=-v_{*}^{\prime}(s) \int_{\left\{u>u_{*}(s)\right\}} g(x) \mathrm{d} x=-v_{*}^{\prime}(s) \int_{0}^{s} g_{* v}(\sigma) d \sigma . \tag{5}
\end{equation*}
$$

## 4 An Abstract Result for the Existence of Critical Value Near Zero.

Due to Ekeland variational principle (see 11]), we shall introduce here an existence result for the case where we have compact embedding from $V$ into $X$. We also introduce the following hypothesis:
H3./ $\Phi(0)=0$, and there exist $u_{1} \in V$ and $\eta>\left\|u_{1}\right\|$ such that

$$
\Phi(v)>0,\|v\|=\eta, \Phi\left(u_{1}\right)<0, \quad \inf _{v \in \bar{B}(0, \eta)} \Phi(v)>-\infty .
$$

Theorem 4.1 Under the conditions H1./ and H3./, if the injection of $V$ into $X$ is compact, then there exists a function $u \not \equiv 0, u \in V$, which is a critical point of $\Phi:=J-j$, that is

$$
0 \in \partial J(u)-\partial j(u)
$$

Proof. Let $B(0, \eta)$ be the open ball of radius $\eta$. Since we have a function $u_{1} \not \equiv 0, u_{1} \in V$ such that $\Phi\left(u_{1}\right)<0$ (by H3./), then $u_{1} \in B(0, \eta)$ and $c=\inf _{v \in \bar{B}(0, \eta)} \Phi(v)$ verifies

$$
-\infty<c \leqslant \Phi\left(u_{1}\right)<0
$$

By Ekeland variational principle (see 22,27$]$ and Appendix in 11]), we have a minimizing sequence $\left(u_{n}\right) \subset \bar{B}(0, \eta)$, and $u \in V$ such that

1. $\Phi\left(u_{n}\right) \xrightarrow[n \rightarrow+\infty]{ } c$, (thus $\left.u_{n} \in \operatorname{interior}\{\bar{B}(0, \eta)\}=B(0, \eta)\right)$,
2. $\ell_{n}^{*} \in \partial \Phi\left(u_{n}\right),\left\|\ell_{n}^{*}\right\|_{V^{\prime}} \xrightarrow[n \rightarrow+\infty]{ } 0$,
3. $u_{n}$ converges weakly to $u$ in $V$,
4. $u_{n}$ converges strongly to $u$ in $X$.

Thus, there exist $w_{n} \in \partial J\left(u_{n}\right), v_{n} \in \partial j\left(u_{n}\right)$ such that

$$
\ell_{n}^{*}=w_{n}-v_{n},
$$

and this implies

$$
\begin{equation*}
<\ell_{n}^{*}, u_{n}-u>=<w_{n}, u_{n}-u>-<v_{n}, u_{n}-u> \tag{6}
\end{equation*}
$$

Thus, for $w \in \partial J(u)$

$$
\begin{equation*}
<\ell_{n}^{*}, u_{n}-u>-<w, u_{n}-u>+<v_{n}, u_{n}-u>=<w_{n}-w, u_{n}-u> \tag{7}
\end{equation*}
$$

Since we have the strong convergence of the sequence $\left(u_{n}\right)$ in $X$, then $\left|u_{n}\right| \leqslant c_{1}$ and $\left|v_{n}\right|_{X^{\prime}} \leqslant c_{2}$, for $v_{n} \in \partial j\left(u_{n}\right)$.
From (7), we then have

$$
\begin{equation*}
\left|<w_{n}-w, u_{n}-u>\left|\leqslant c_{3}\left\|\ell_{n}^{*}\right\|_{V^{\prime}}+\left|<w, u_{n}-u>\left|+c_{2}\right| u_{n}-u\right| .\right.\right. \tag{8}
\end{equation*}
$$

The above convergences, together with relation (8), yield:

$$
\begin{equation*}
\lim _{n \rightarrow+\infty}<w_{n}-w, u_{n}-u>=0, \quad \text { for } w_{n} \in \partial J\left(u_{n}\right) \text { and } w \in \partial J(u) \tag{9}
\end{equation*}
$$

By the assumption H1./, we conclude that $u_{n}$ converges strongly to $u$ in $V$. Therefore, $\Phi\left(u_{n}\right) \xrightarrow[n \rightarrow+\infty]{ } \Phi(u)=c<0$.

### 4.1 Example of Applications of Theorem 4.1

Let $\delta_{1}>0, \ldots, \delta_{N}>0$ be $N$ real numbers and $q_{i}, p_{i}, i=1, \ldots, N$ be $2 N$ bounded measurable functions on $\Omega$ satisfying:

$$
1<q_{i_{-}}:=\underset{\Omega}{\operatorname{essinf}} q_{i} \leqslant q_{i}(x)<p_{i_{-}}:=\underset{\Omega}{\operatorname{essinf}} p_{i} \leqslant p_{i_{+}}:=\underset{\Omega}{\operatorname{esssup}} p_{i}<+\infty
$$

Consider

$$
\varphi_{i}(x, t):=\left\{\begin{array}{ll}
|t|^{p_{i}(x)}, & \text { if }|t|>\delta_{i}, \\
\alpha_{i}(x)|t|^{q_{i}(x)}, & \text { if }|t| \leqslant \delta_{i},
\end{array} x \in \Omega, t \in \mathbb{R}, \alpha_{i}(x)=\left(\delta_{i}\right)^{\left(p_{i}-q_{i}\right)(x)}\right.
$$

We can choose $\phi_{i}(x, t)$ as follows:

$$
\phi_{i}(x, t):= \begin{cases}p_{i}(x)|t|^{p_{i}(x)-2} t, & \text { if }|t|>\delta_{i}, \\ q_{i}(x)|t|^{q_{i}(x)-2} t, & \text { if }|t|<\delta_{i} \\ p_{i}(x) \delta_{i}^{p_{i}(x)-1}, & \text { if } t=\delta_{i} \\ -p_{i}(x) \delta_{i}^{p_{i}(x)-1}, & \text { if } t=-\delta_{i}\end{cases}
$$

One can check that all the assumptions A1./ to A3./ are fulfilled for $\underline{\alpha}=q_{-}^{-}:=\min _{1 \leqslant i \leqslant N}\left\{q_{i_{-}}\right\}$and $\bar{\alpha}=p_{+}^{+}:=\max _{1 \leqslant i \leqslant N}\left\{p_{i_{+}}\right\}$. We also have:

$$
\partial \varphi_{i}(x, t)= \begin{cases}\phi_{i}(x, t), & \text { if }|t|>\delta_{i} \text { or }|t|<\delta_{i} \\ \delta_{i}^{p_{i}(x)-1}\left[q_{i}(x), p_{i}(x)\right] \operatorname{sign}(t), & \text { otherwise }\end{cases}
$$

We define the function $J: \mathbf{V}_{0} \rightarrow \mathbb{R}$ as follows

$$
J(v):=\sum_{i=1}^{N} \int_{\Omega} \varphi_{i}\left(x, \frac{\partial v}{\partial x_{i}}(x)\right) \frac{\mathrm{d} x}{p_{i}(x)} .
$$

Theorem 4.2 Let $\delta_{M}>0$ be a real number and $p_{M}, q_{M}$ be two bounded measurable functions on $\Omega$ satisfying:

$$
1<q_{M_{-}}:=\underset{\Omega}{\operatorname{essinf}} q_{M}(x) \leqslant q_{M}(x)<p_{M_{-}}:=\underset{\Omega}{\operatorname{essinf}} p_{M}(x) .
$$

Assume that $\mathbf{V}_{0}$ be compactly embedded in $L^{\varphi_{M}}(\Omega)$ and

$$
q_{M_{-}}<q_{-}^{-}
$$

Then, there exists $\lambda_{*}>0$, such that $\left.\forall \lambda \in\right] 0, \lambda_{*}[$, there exists a non-trivial function $u \in \mathbf{V}_{0}$ such that

$$
\sum_{i=1}^{N} \int_{\Omega} w_{i}(x) \frac{\partial v}{\partial x_{i}}(x) \mathrm{d} x=\lambda \int_{\Omega} w_{M}(x) v(x) \mathrm{d} x, \quad \forall v \in \mathbf{V}_{0}
$$

with $p_{i}(x) w_{i}(x) \in \partial \varphi_{i}\left(x, \frac{\partial u}{\partial x_{i}}(x)\right)$ and $\quad p_{M}(x) w_{M}(x) \in \partial \varphi_{M}(x, u(x))$ a.e., where

$$
\varphi_{M}(x, u(x))= \begin{cases}|u(x)|^{p_{M}(x)}, & \text { if }|u(x)|>\delta_{M}, \\ \alpha_{M}(x)|u(x)|^{q_{M}(x)}, & \text { if }|u(x)| \leqslant \delta_{M},\end{cases}
$$

where $\alpha_{M}(x)=\left(\delta_{M}\right)^{\left(p_{M}-q_{M}\right)(x)}$.
Proof. Introducing

$$
\Phi_{\lambda}(u)=J(u)-\lambda j(u), \quad j(u)=\int_{\Omega} \varphi_{M}(x, u(x)) \frac{\mathrm{d} x}{p_{M}(x)}
$$

one can check all assumptions of Theorem 4.1 (for more details, see [23]).

### 4.2 Other Example (with coerciveness)

Theorem 4.3 Under the same notations of Section 4.1, assume that $\mathbf{V}_{0}$ be compactly embedded in $L^{\varphi_{M}}(\Omega)$ and

$$
q_{M_{-}}<p_{M_{+}}<q_{-}^{-}
$$

Then, there exist $\lambda_{*}>0$ and $\lambda_{* *}>0$, such that $\left.\forall \lambda \in\right] 0, \lambda_{*}[\cup] \lambda_{* *},+\infty[$, there exists a non-trivial function $u \in \mathbf{V}_{0}$ such that

$$
\sum_{i=1}^{N} \int_{\Omega} w_{i}(x) \frac{\partial v}{\partial x_{i}}(x) \mathrm{d} x=\lambda \int_{\Omega} w_{M}(x) v(x) \mathrm{d} x, \quad \forall v \in \mathbf{V}_{0}
$$

with $p_{i}(x) w_{i}(x) \in \partial \varphi_{i}\left(x, \frac{\partial u}{\partial x_{i}}(x)\right) \quad$ and $\quad p_{M}(x) w_{M}(x) \in \partial \varphi_{M}(x, u(x))$ a.e. in $\Omega$.

Proof. The existence of $\lambda_{*}>0$ such that any $\left.\lambda \in\right] 0, \lambda_{*}[$ is an eigenvalue is an immediate consequence of Theorem4.2. In order to prove the second part of Theorem 4.3, we will show that, for $\lambda$ positive and large enough, the functional $\Phi_{\lambda}$ possesses a non-trivial global minimum point in $\mathbf{V}_{0}$.

First, the function $\Phi_{\lambda}$ is coercive on $\mathbf{V}_{0}$. Indeed, if $\max _{1 \leqslant i \leqslant N}\left\|\frac{\partial u}{\partial x_{i}}\right\|_{\Phi_{i}} \geqslant 1$, then
$J(u)=\sum_{i=1}^{N} \int_{\Omega} \varphi_{i}\left(x, \frac{\partial u}{\partial x_{i}}(x)\right) \frac{\mathrm{d} x}{p_{i}(x)} \geqslant \frac{1}{p_{+}^{+}} \cdot \frac{1}{N^{q_{-}^{-}}} \cdot\|u\|_{\mathbf{V}_{0}}^{q_{-}^{-}}$, (by Corollary 5.1).

Moreover, we have $\forall u \in \mathbf{V}_{0}$,

$$
\int_{\Omega} \varphi_{M}(x, u(x)) \mathrm{d} x \leqslant\left(S_{0}\right)^{q_{M-}}\|u\|_{\mathbf{V}_{0}}^{q_{M-}}+\left(S_{0}\right)^{p_{M+}}\|u\|_{\mathbf{V}_{0}}^{p_{M+}}
$$

where $S_{0}>0$ is the Sobolev constant of the injection $\mathbf{V}_{0}$ into $L^{\varphi_{M}}(\Omega)$. Then,

$$
\Phi_{\lambda}(u) \geqslant \frac{1}{p_{+}^{+} \cdot N^{q_{-}^{-}}} \cdot\|u\|_{\mathbf{V}_{0}}^{q_{-}^{-}}-\frac{\lambda\left(S_{0}\right)^{q_{M_{-}}}}{p_{M_{-}}}\|u\|_{\mathbf{V}_{0}}^{q_{M_{-}}}+\frac{\lambda\left(S_{0}\right)^{p_{M_{+}}}}{p_{M_{-}}}\|u\|_{\mathbf{V}_{0}}^{p_{M_{+}}},
$$

for all $u \in \mathbf{V}_{0}$ such that $\max _{1 \leqslant i \leqslant N}\left\|\frac{\partial u}{\partial x_{i}}\right\|_{\varphi_{i}} \geqslant 1$.
Since we have $q_{M_{-}}<p_{M_{+}}<q_{-}^{-}$, then $\Phi_{\lambda}(u) \xrightarrow{\|u\|_{\mathbf{v}_{0} \rightarrow+\infty}}+\infty$.
On the other hand, the same arguments as in the proof of Lemma 3.4 of 28 can be used in order to show that $\Phi_{\lambda}$ is weakly lower semi-continuous on $\mathbf{V}_{0}$ (see also [23). The functional $\Phi_{\lambda}$ is also coercive on $\mathbf{V}_{0}$. These two facts enable us to apply the first result of Section 2.1.1 in 22] in order to find that there exists $u_{0} \in \mathbf{V}_{0}$, a global minimizer of $\Phi_{\lambda}$.

Finally, we have to show that $u_{0}$ is a non-trivial solution for $\lambda$ large enough. Indeed, letting $t_{0}>\max \left\{1 ; \delta_{M}\right\}$ be a fixed real number and $\Omega_{1}$ be an open subset of $\Omega$ with $\Omega_{1} \subset \subset \Omega$ and $\left|\Omega_{1}\right|>0$, we deduce that there exists $v_{0} \in C_{c}^{\infty}(\Omega) \subset \mathbf{V}_{0}$ such that

$$
\left\{\begin{array}{l}
v_{0}(x)=t_{0}, \quad \text { if } x \in \bar{\Omega}_{1}, \\
0 \leqslant v_{0}(x) \leqslant t_{0}, \text { if } x \in \Omega \backslash \Omega_{1} .
\end{array}\right.
$$

We have

$$
\begin{aligned}
\Phi_{\lambda}\left(v_{0}\right) & =\sum_{i=1}^{N} \int_{\Omega} \varphi_{i}\left(x, \frac{\partial v_{0}}{\partial x_{i}}(x)\right) \frac{\mathrm{d} x}{p_{i}(x)}-\lambda \int_{\Omega} \varphi_{M}\left(x, v_{0}(x)\right) \frac{\mathrm{d} x}{p_{M}(x)} \\
& \leqslant \frac{1}{p_{-}^{-}} \sum_{i=1}^{N} \int_{\Omega} \varphi_{i}\left(x, \frac{\partial v_{0}}{\partial x_{i}}(x)\right) \mathrm{d} x-\frac{\lambda}{p_{M_{+}}} \int_{\Omega_{1}}\left|v_{0}\right|^{p_{M}(x)} \mathrm{d} x \\
& \leqslant \frac{1}{p_{-}^{-}} \sum_{i=1}^{N} \int_{\Omega} \varphi_{i}\left(x, \frac{\partial v_{0}}{\partial x_{i}}(x)\right) \mathrm{d} x-\frac{\lambda}{p_{M_{+}}} \int_{\Omega_{1}}\left(t_{0}\right)^{p_{M}-\mathrm{d} x} \\
& \leqslant C_{1}-\frac{\lambda}{p_{M+}}\left(t_{0}\right)^{p_{M-}}\left|\Omega_{1}\right|
\end{aligned}
$$

where $C_{1}>0$ is a positive constant. Thus, there exists $\lambda_{* *}=\frac{C_{1} p_{M+}}{\left(t_{0}\right)^{p_{M}-}\left|\Omega_{1}\right|}>0$ such that $\Phi_{\lambda}\left(v_{0}\right)<0$, for any $\lambda>\lambda_{* *}$. It follows that $\Phi_{\lambda}\left(u_{0}\right)<0$, for any $\lambda>\lambda_{* *}$ and thus $u_{0}$ is a non-trivial solution for $\lambda$ large enough.

Remark 4.1 Let $f \in \mathbf{V}_{0}^{\prime}$ be an element of the dual space of $\mathbf{V}_{0}$ and consider the following problem:

$$
\begin{equation*}
-\operatorname{div}_{\vec{\rho}}\left(\partial \varphi_{i}\left(x, \frac{\partial u}{\partial x_{i}}(x)\right)\right)=f \tag{10}
\end{equation*}
$$

where all assumptions A1./ to A3./ are satisfied. Then, there exists a global minimizer $u \in \mathbf{V}_{0}$ and $u$ is a solution of (10). Indeed, if we replace the function $j(v)$ of Theorem 4.3 by $<f, v>$ and we use the same arguments as in the proof of Theorem 4.3. we show that the functional $\Phi$ defined by

$$
\Phi(v):=J(v)-<f, v>, \quad v \in \mathbf{V}_{0}
$$

is coercive and weakly lower semi-continuous.

## 5 Minimization Problem with Constraint.

In order to prove the existence for a minimization problem with constraint related to the fully discontinuous operator, we shall start by using the nonsmooth version of the Lagrange Multiplier Theorem (see [9]). Due to the inhomogeneity, our operator is more complicated than the $p$-Laplacian.
Let $\Omega$ be a bounded Lipschitz open set of $\mathbb{R}^{N}$ and consider $N$ borelian functions $\phi_{i}: \Omega \times \mathbb{R} \rightarrow \mathbb{R}$, such that $\phi_{i}$ satisfies A1./ and A2./.
We define the $N$-function $\varphi_{i}$ on $\Omega \times \mathbb{R}$ :

$$
\varphi_{i}(x, t):=\int_{0}^{|t|} \phi_{i}(x, \sigma) \mathrm{d} \sigma
$$

We also assume that $\varphi_{i}$ satisfies A3./. Moreover, we consider the function $J$ on $\mathbf{V}_{0}$, as follows

$$
J(v):=\sum_{i=1}^{N} \int_{\Omega} \varphi_{i}\left(x, \frac{\partial v}{\partial x_{i}}(x)\right) \mathrm{d} x .
$$

Theorem 5.1 Under the above conditions, assume that $\mathbf{V}_{0}$ be continuously embedded in $X$. Let $j: X \rightarrow \mathbb{R}$ be an even and convex function such that $j(0)=0$. If we suppose
(i) $j$ be a continuous function and $\mathbf{V}_{0}$ be compactly embedded in $X$,
or
(ii) $j$ be weakly-continuous function,
then, there exist $u_{1} \in \mathbf{V}_{0}, u_{1} \geqslant 0, u_{1} \not \equiv 0$ and $\lambda_{1}>0$ such that

$$
0 \in \partial J\left(u_{1}\right)-\lambda_{1} \partial j\left(u_{1}\right)
$$

We start with two auxiliary results, and we recall the relation between the modular function and the norm in the Orlicz spaces.

Lemma 5.1 23. Let $u \in L^{\varphi_{i}}(\Omega)$. We have the following properties:
(1) If $\|u\|_{\varphi_{i}} \geqslant 1$, then $\|u\|_{\varphi_{i}}^{\frac{\alpha}{\varphi_{i}}} \leqslant \int_{\Omega} \varphi_{i}(x, u(x)) \mathrm{d} x \leqslant\|u\|_{\varphi_{i}}^{\bar{\alpha}}$.
(2) If $\|u\|_{\varphi_{i}}<1$, then $\|u\|_{\varphi_{i}}^{\bar{\alpha}} \leqslant \int_{\Omega} \varphi_{i}(x, u(x)) \mathrm{d} x \leqslant\|u\|_{\varphi_{i}}^{\frac{\alpha}{\varphi_{i}}}$.

As a consequence of Lemma 5.1, we have
Corollary 5.1 [23]. Let $u \in \mathbf{V}_{0}$. Then:
(1') If $\max _{1 \leqslant i \leqslant N}\left\|\frac{\partial u}{\partial x_{i}}\right\|_{\varphi_{i}} \geqslant 1$, then $\frac{1}{N \underline{\alpha}} \cdot\|u\|_{\mathbf{V}_{0}}^{\frac{\alpha}{\alpha}} \leqslant J(u) \leqslant N \cdot\|u\|_{\mathbf{V}_{0}}^{\bar{\alpha}}$.
(2') If $\max _{1 \leqslant i \leqslant N}\left\|\frac{\partial u}{\partial x_{i}}\right\|_{\varphi_{i}}<1$, then $\frac{1}{N^{\bar{\alpha}}} \cdot\|u\|_{\mathbf{V}_{0}}^{\bar{\alpha}} \leqslant J(u) \leqslant N \cdot\|u\|_{\mathbf{V}_{0}}^{\alpha}$.

## Proof of Theorem 5.1:

Let $\alpha>0$ be fixed. We are in a position now to show that there exists $u_{1} \in \mathbf{V}_{0}$, $u_{1} \geqslant 0$ and $u_{1} \not \equiv 0$ such that

$$
J\left(u_{1}\right)=\inf \{J(v): j(v)=\alpha\} \geqslant 0 .
$$

For this, we define

$$
m:=\inf \{J(v): j(v)=\alpha\} \quad \text { and } \quad S:=\left\{u \in \mathbf{V}_{0}: j(u)=\alpha\right\}
$$

We consider a minimizing sequence $\left(v_{n}\right)$ in $S$ such that

$$
\begin{equation*}
J\left(v_{n}\right) \xrightarrow[n \rightarrow+\infty]{ } m \tag{11}
\end{equation*}
$$

By Corollary 5.1, $\left(v_{n}\right)$ is bounded in $\mathbf{V}_{0}$. Then, there exists a subsequence of $\left(v_{n}\right)$, still denoted by $\left(v_{n}\right)$, that converges weakly in $\mathbf{V}_{0}$. The function $J$ is weakly lower semi-continuous on $\mathbf{V}_{0}$ (see 23$)$, so we deduce that

$$
\begin{equation*}
J(u) \leqslant \liminf _{n \rightarrow+\infty} J\left(v_{n}\right)=m \tag{12}
\end{equation*}
$$

First, we suppose that (i) holds. Then, using the compact embedding and passing to a subsequence, if necessary, we deduce that $\left(v_{n}\right)$ converges strongly in $X$. Moreover, by the continuity of $j, S$ is closed. This implies that $u \in S$. Then,

$$
\begin{equation*}
J(u)=m \tag{13}
\end{equation*}
$$

We also suppose that (ii) holds. By the weak-continuity of $j$, we deduce that $j\left(v_{n}\right)=\alpha \xrightarrow[n \rightarrow+\infty]{ } j(u)=\alpha$ and we also have (13).

On the other hand, exploiting Lagrange Multiplier Theorem (see [9]), we then get the existence of $(t, s) \neq(0,0)$, such that $t \geqslant 0$ and

$$
\begin{equation*}
0 \in t \partial J\left(u_{1}\right)+s \partial j\left(u_{1}\right), \quad u_{1}=|u| \geqslant 0 \tag{14}
\end{equation*}
$$

We observe that $t \neq 0$. Indeed, if we suppose that $t=0$, then

$$
0 \in s \partial j\left(u_{1}\right) \text { and } s \neq 0
$$

We obtain

$$
\begin{equation*}
0 \in \partial j\left(u_{1}\right) \tag{15}
\end{equation*}
$$

which is impossible since $\left\langle\partial j\left(u_{1}\right) ; u_{1}\right\rangle \geqslant \alpha>0$. We then get $t>0$ and

$$
\begin{equation*}
0 \in \partial J\left(u_{1}\right)-\lambda_{1} \partial j\left(u_{1}\right), \text { where } \lambda_{1}=-\frac{s}{t} \tag{16}
\end{equation*}
$$

Finally, we point out that there exist $w_{J}^{*} \in \partial J\left(u_{1}\right)$ and $w_{j}^{*} \in \partial j\left(u_{1}\right)$ such that

$$
\begin{equation*}
w_{J}^{*}=\lambda_{1} w_{j}^{*} \tag{17}
\end{equation*}
$$

Using the above equality, we find $\lambda_{1}=\frac{\left\langle w_{J}^{*} ; u_{1}\right\rangle}{\left\langle w_{j}^{*} ; u_{1}\right\rangle}$. We note that $\lambda_{1}>0$. Indeed, we have $\left\langle w_{j}^{*} ; u_{1}\right\rangle \geqslant \alpha>0$. And there exists $w_{i}^{*}(x) \in \partial \varphi_{i}\left(x, \frac{\partial u_{1}}{\partial x_{i}}(x)\right)$ a.e. $x \in \Omega$, for $i=1, \ldots, N$ (see Lemma 4.4 in [8) such that

$$
\begin{aligned}
\left\langle w_{J}^{*} ; u_{1}\right\rangle & =\sum_{i=1}^{N} \int_{\Omega} w_{i}^{*}(x) \frac{\partial u_{1}}{\partial x_{i}}(x) \mathrm{d} x \\
& \geqslant \underline{\alpha} \sum_{i=1}^{N} \int_{\Omega} \varphi_{i}\left(x, \frac{\partial u_{1}}{\partial x_{i}}(x)\right) \mathrm{d} x \\
& \geqslant \underline{\alpha} J\left(u_{1}\right) \geqslant 0
\end{aligned}
$$

If $\lambda_{1}=0$, then $J\left(u_{1}\right)=0$. By Corollary 5.1, we deduce that $\left\|u_{1}\right\|_{\mathbf{V}_{0}}=0$, which is impossible since $u_{1} \in S$. This implies $\lambda_{1}>0$.
For more examples of applications of Theorem 5.1] see 23.

Remark 5.1 In the case of p-Laplacian, the homogeneity of the operator allows to prove that $\lambda_{1}$ is the first eigenvalue.

## 6 Resonant Case Near Zero.

In this section, we prove the existence of solutions for an eigenvalue problem, where the potential $j$ has a partial interaction at zero with the best Sobolev constant (see (j4)).
Let $\Omega$ be a bounded Lipschitz open set of $\mathbb{R}^{N}$ and consider $N$ borelian functions $\phi_{i}: \Omega \times \mathbb{R} \rightarrow \mathbb{R}$, for $i=1, \ldots, N$ and $\phi_{M}: \Omega \times \mathbb{R} \rightarrow \mathbb{R}$, such that $\phi_{i}$ and $\phi_{M}$ satisfy A1./ and A2./. We define on $\Omega \times \mathbb{R}$ the $N$-functions

$$
\varphi_{i}(x, t):=\int_{0}^{|t|} \phi_{i}(x, \sigma) \mathrm{d} \sigma, \quad \text { and } \quad \varphi_{M}(x, t):=\int_{0}^{|t|} \phi_{M}(x, \sigma) \mathrm{d} \sigma
$$

And we assume that $\varphi_{i}$ and $\varphi_{M}$ satisfy A3./ i.e.
There exist $\underline{\alpha}>1, \bar{\alpha}>1, \underline{\beta}>1$ and $\bar{\beta}>1$ such that, for a.e. $x \in \Omega, \forall t \in \mathbb{R}$ and $\forall w_{i}^{*}(x, t) \in \partial \varphi_{i}(x, t)$, we have

$$
\underline{\alpha} \varphi_{i}(x, t) \leqslant t w_{i}^{*}(x, t) \leqslant \bar{\alpha} \varphi_{i}(x, t), \quad \forall 1 \leqslant i \leqslant N .
$$

For every $w_{M}^{*}(x, t) \in \partial \varphi_{M}(x, t)$, we have

$$
\underline{\beta} \varphi_{M}(x, t) \leqslant t w_{M}^{*}(x, t) \leqslant \bar{\beta} \varphi_{M}(x, t) .
$$

We define the Banach-Sobolev function space $\mathbf{V}_{0}:=W_{0}^{1, \varphi_{1}, \ldots, \varphi_{N}}(\Omega)$ as

$$
\mathbf{V}_{0}:=\left\{v \in W_{0}^{1,1}(\Omega): \sum_{i=1}^{N}\left(\int_{\Omega} \varphi_{i}\left(x, \frac{\partial v}{\partial x_{i}}(x)\right) \mathrm{d} x\right)<+\infty\right\}
$$

which is endowed with the norm $\|v\|_{\mathbf{V}_{0}}=\sum_{i=1}^{N}\left\|\frac{\partial v}{\partial x_{i}}\right\|_{\varphi_{i}}$.
Consider $J: \mathbf{V}_{0} \rightarrow \mathbb{R}$ with $J(v)=\sum_{i=1}^{N} \int_{\Omega} \varphi_{i}\left(x, \frac{\partial v}{\partial x_{i}}(x)\right) \mathrm{d} x$.
Theorem 6.1 deals with the existence of solutions $u \in \mathbf{V}_{0}$ of 18 under the next hypotheses on the nonsmooth potential $j$.
Theorem 6.1 Under the above conditions, let $j: \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ be such that:
( $\mathbf{j 1}$ ) $x \mapsto j(x, \xi)$ is measurable for all $\xi \in \mathbb{R}$.
$\xi \mapsto j(x, \xi)$ is locally Lipschitz for a.e. $x \in \Omega$.
(j2) There exists a constant $a_{1}>0$, such that

$$
|j(x, \xi)| \leqslant a_{1}\left(|\xi|+\varphi_{M}(x, \xi)\right), \quad \text { a.e. } x \in \Omega \text { and for all } \xi \in \mathbb{R} \text {. }
$$

(j3) There exist some constants $M>0, \beta>0$ and $k_{1}>0$, such that

$$
k_{1}|\xi|^{\beta} \leqslant j(x, \xi), \quad \forall|\xi| \geqslant M
$$

(j4) There exists a constant $0<c^{*}<\frac{1}{N^{\bar{\alpha}} \cdot\left(S_{2}\right)^{\bar{\alpha}}}$, such that

$$
j(x, \xi) \leqslant c^{*}|\xi|^{\bar{\alpha}}, \quad \text { in a neighborhood of } \xi=0
$$

where $S_{2}>0$ is the Sobolev constant of the embedding $\mathbf{V}_{0} \subset L^{\bar{\alpha}}(\Omega)$.
(j5) We have the following growth properties:
(1) $\exists c_{0} \geqslant 0: \beta g(u) \leqslant \inf _{v^{*} \in \partial g(u)}\left\langle v^{*} ; u\right\rangle+c_{0} \beta, \quad \forall u \in L^{\varphi_{M}}(\Omega)$, where $g(u)=\int_{\Omega} j(x, u(x)) \mathrm{d} x$.
(2) There exist constants $c_{1}>0, c_{2} \geqslant 0$ :

$$
\frac{1}{\beta} \sup _{w^{*} \in \partial J(u)}\left\langle w^{*} ; u\right\rangle-c_{2}+c_{1}\|u\|_{V} \leqslant J(u), \quad \forall u \in \mathbf{V}_{0}
$$

If the injection $\mathbf{V}_{0} \subset L^{\varphi_{M}}(\Omega)$ is compact and if $\bar{\alpha}<\beta<\underline{\beta}$, then, there exists $u \in \mathbf{V}_{0}$ a non-trivial function, such that

$$
\begin{equation*}
0 \in \partial J(u)-\partial g(u) \tag{18}
\end{equation*}
$$

We start with two auxiliary results:
Lemma 6.1 Assume that (j1), (j2) and (j4) hold, then, there exist $\eta>0$ and $\alpha>0$ such that

$$
\Phi(u):=J(u)-g(u) \geqslant \alpha, \quad \text { for all } u \in \mathbf{V}_{0} \text { with }\|u\|_{\mathbf{V}_{0}}=\eta
$$

Proof. First, by (j4), there exists $0<\delta \ll 1$ such that

$$
\begin{equation*}
j(x, \xi) \leqslant c^{*}|\xi|^{\bar{\alpha}}, \quad \text { for all }|\xi| \leqslant \delta \tag{19}
\end{equation*}
$$

By ( $\mathbf{j} 2$ ), we get that, for a.e. $x \in \Omega$, for all $\xi \in \mathbb{R}$ with $|\xi|>\delta$ and for all $w_{M}^{*}(x, \xi) \in \partial \varphi_{M}(x, \xi):$

$$
\begin{aligned}
|j(x, \xi)| & \leqslant a_{1}\left(|\xi|+\varphi_{M}(x, \xi)\right) \\
& \leqslant a_{1}\left(\frac{\bar{\beta}}{w_{M}^{*}(x, \delta)}+1\right) \varphi_{M}(x, \xi)
\end{aligned}
$$

It follows that there exists a constant $c(\delta)>0$ independent of $\xi$, such that

$$
\begin{equation*}
j(x, \xi) \leqslant c^{*}|\xi|^{\bar{\alpha}}+c(\delta) \varphi_{M}(x, \xi), \quad \forall \xi \in \mathbb{R} \tag{20}
\end{equation*}
$$

We recall that we have (see Remark 3.3)

$$
\begin{equation*}
\mathbf{V}_{0} \subset L^{\varphi_{M}}(\Omega) \subset L^{\underline{\beta}}(\Omega) \subset L^{\bar{\alpha}}(\Omega) \tag{21}
\end{equation*}
$$

Let $0<\eta<\min \left\{1 ; \frac{1}{S_{0}}\right\}$ be fixed (small enough). Thus, by Corollary 5.1. we get:

$$
J(u) \geqslant \frac{1}{N^{\bar{\alpha}}} \cdot\|u\|_{\mathbf{V}_{0}}^{\bar{\alpha}}, \quad \text { for all }\|u\|_{\mathbf{V}_{0}}=\eta
$$

where $S_{0}>0$ is the Sobolev constant of the embedding $\mathbf{V}_{0} \subset L^{\varphi_{M}}(\Omega)$.
On the other hand, there exists $\delta_{1}>0$ such that, for all $u$ satisfying $\|u\|_{\mathbf{v}_{0}}=\eta$, we have:

$$
\begin{aligned}
\Phi(u) & \geqslant \frac{1}{N^{\bar{\alpha}}} \cdot\|u\|_{\mathbf{V}_{0}}^{\bar{\alpha}}-c^{*}\|u\|_{L^{\bar{\alpha}}}^{\bar{\alpha}}-\delta_{1} \int_{\Omega} \varphi_{M}(x, u(x)) \mathrm{d} x \\
& \geqslant \frac{1}{N^{\bar{\alpha}}} \cdot\|u\|_{\mathbf{V}_{0}}^{\bar{\alpha}}-c^{*}\left(S_{2}\right)^{\bar{\alpha}}\|u\|_{\mathbf{V}_{0}}^{\bar{\alpha}}-\delta_{1}\|u\|_{\bar{\varphi}_{M}}^{\beta} \\
& \geqslant\left(\frac{1}{N^{\bar{\alpha}}}-c^{*}\left(S_{2}\right)^{\bar{\alpha}}\right)\|u\|_{\mathbf{V}_{0}}^{\bar{\alpha}}-\delta_{1}\left(S_{0}\right)-\underline{\beta}\|u\|_{\mathbf{V}_{0}}^{\beta}
\end{aligned}
$$

Finally, since $c^{*}<\frac{1}{N^{\bar{\alpha}} \cdot\left(S_{2}\right)^{\bar{\alpha}}}$ and $\bar{\alpha}<\underline{\beta}$, then, for $\eta>0$ small enough, the lemma is proved.

Lemma 6.2 Assume that (j1), (j2) and (j3) hold, then, there exists $u_{0} \in \mathbf{V}_{0}$ such that

$$
\Phi\left(u_{0}\right)<\alpha \quad \text { and } \quad\left\|u_{0}\right\|_{\mathbf{v}_{0}}>\eta .
$$

Proof. First, by (j3), we have

$$
k_{1}|\xi|^{\beta} \leqslant j(x, \xi), \quad \forall|\xi| \geqslant M .
$$

Consider $u \in \mathbf{V}_{0}$, then there exists $k_{2}>0$, such that

$$
\begin{aligned}
k_{1} \int_{\Omega}|u|^{\beta} \mathrm{d} x & =k_{1} \int_{\{|u| \geqslant M\}}|u|^{\beta} \mathrm{d} x+k_{1} \int_{\{|u|<M\}}|u|^{\beta} \mathrm{d} x \\
& \leqslant \int_{\{|u| \geqslant M\}} j(x, u(x)) \mathrm{d} x+k_{2} .
\end{aligned}
$$

On the other hand, by ( $\mathbf{j} \mathbf{2}$ ), there exists $k_{3}>0$ such that

$$
\begin{aligned}
-g(u) & \leqslant-\int_{\{|u| \geqslant M\}} j(x, u(x)) \mathrm{d} x+\int_{\{|u|<M\}}|j(x, u(x))| \mathrm{d} x \\
& \leqslant-k_{1} \int_{\Omega}|u|^{\beta} \mathrm{d} x+k_{2}+k_{3} \\
& =-k_{1}\|u\|_{L^{\beta}}^{\beta}+k_{4} .
\end{aligned}
$$

Taking $t>1$ and using Remark 3.3, we find

$$
\Phi(t u) \leqslant t^{\bar{\alpha}} J(u)-k_{1} \cdot t^{\beta}\|u\|_{L^{\beta}}^{\beta}+k_{4} .
$$

Finally, since $\bar{\alpha}<\beta$, we deduce that

$$
\Phi(t u) \xrightarrow[t \rightarrow+\infty]{ }-\infty
$$

Letting $t_{0}>1$ large enough and defining $u_{0}:=t_{0} u \in \mathbf{V}_{0}$, we get

$$
\Phi\left(u_{0}\right)<\alpha \quad \text { and } \quad\left\|u_{0}\right\|_{\mathbf{V}_{0}}>\eta .
$$

The proof of Lemma 6.2 is complete.
Proof of Theorem 6.1:
At this stage, using Lemma 6.1 and Lemma 6.2, we are able to apply SHI's result (see [27]) and we deduce the existence of a Palais-Smale sequence denoted by ( $u_{n}$ ) in $\mathbf{V}_{0}$.
We end the proof of Theorem 6.1 by using ( $\mathbf{j} \mathbf{5}$ ), which allows us to apply Lemma 3.1.

## 7 Qualitative Properties of Eigenvectors Related to $\bar{\rho}^{>}$-multivalued Leray-Lions Operators.

In this section, we are interested in showing the qualitative properties for the solutions of the eigenvalue problems related to $\bar{\rho}^{>}$-multivalued Leray-Lions operators.
Let $\varphi_{i}: \Omega \times \mathbb{R} \rightarrow \mathbb{R}, i=1, \ldots, N$ and $\varphi_{M}: \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ be $N+1$ functions for which the assumptions A.1/-A.3/ are verified. We consider the OrliczSobolev space $W_{0}^{1, \varphi_{1}, \ldots, \varphi_{N}}(\Omega)$ and let $u \in W_{0}^{1, \varphi_{1}, \ldots, \varphi_{N}}(\Omega) \subset L^{\varphi_{M}}(\Omega), u \geqslant 0$ be a solution of the following problem:

$$
\begin{equation*}
-\operatorname{div}\left(\partial \varphi_{i}\left(x, \frac{\partial u}{\partial x_{i}}\right)\right)=\lambda w_{M}^{*} \tag{22}
\end{equation*}
$$

where

$$
w_{M}^{*}(x) \in \partial \varphi_{M}(x, u(x)) \text { a.e. } x \in \Omega .
$$

The subject of the next theorem is to study the $L^{\infty}$-regularity of the solutions of such problems.

Theorem 7.1 Let $\tau$ and $\alpha$ be two real numbers such that $1<\tau<\alpha<+\infty$.
Consider $\varphi_{i}: \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ defined by

$$
\varphi_{i}(x, t):= \begin{cases}|t|^{\tau}, & \text { if }|t| \leqslant 1 \\ |t|^{\alpha}, & \text { if }|t|>1\end{cases}
$$

Then, there exist $\lambda_{1}>0$ and $u \in W_{0}^{1, \alpha}(\Omega), u \geqslant 0$, solution of the following problem:

$$
\begin{equation*}
-\operatorname{div}\left(\partial \varphi_{i}\left(x, \frac{\partial u}{\partial x_{i}}\right)\right)=\lambda_{1} u^{\alpha-1} \tag{23}
\end{equation*}
$$

Furthermore, if

1. $1 \leqslant N \leqslant 5$,
or
2. $N \geqslant 6$ and $\begin{cases}1<\alpha<\alpha_{N}^{-}, & \text {where } \alpha_{N}^{-}=\frac{N+1-\sqrt{(N-3)^{2}-8}}{4}, \\ \text { or } \\ \alpha_{N}^{+}<\alpha<N, & \text { where } \alpha_{N}^{+}=\frac{N+1+\sqrt{(N-3)^{2}-8}}{4},\end{cases}$
then $u \in L^{\infty}(\Omega)$.
For the reader's convenience, the proof of Theorem 7.1 is divided into several steps:

Lemma 7.1 Under the assumptions of Theorem 7.1, there exist $\lambda_{1}>0$ and $u \in W_{0}^{1, \alpha}(\Omega), u \geqslant 0$, solution of (23).

Proof. The function $j: L^{\alpha}(\Omega) \rightarrow \mathbb{R}$ defined by $j(v):=\frac{1}{\alpha} \int_{\Omega}|v|^{\alpha} \mathrm{d} x$ is a convex, continuous, even function and $j(0)=0 . W_{0}^{1, \alpha}(\Omega) \subset L^{\alpha}(\Omega)$ is a compact embedding, so we can use Theorem 5.1 to achieve the proof.

Lemma 7.2 Let $u$ be a solution of (23), then $u$ verifies the following inequality:

$$
\begin{equation*}
\left(|\nabla u|^{\alpha}\right)_{* u}(s) \leqslant \lambda_{1 N}\left(-\frac{d u_{*}}{d s}(s)\right) \int_{0}^{s} u_{*}^{\alpha-1}(t) d t+c_{2} \tag{24}
\end{equation*}
$$

where $\lambda_{1 N}$ and $c_{2}$ are two positive constants.

Proof. Since $u$ satisfies $\sqrt{23}$, then, there exist

$$
\begin{array}{r}
w_{i}^{*}(x) \in \partial \varphi_{i}\left(x, \frac{\partial u}{\partial x_{i}}(x)\right) \text { a.e., for } i=1, \ldots, N \text {, such that } \\
\sum_{i=1}^{N} \int_{\Omega} w_{i}^{*}(x) \frac{\partial \phi}{\partial x_{i}}(x) \mathrm{d} x=\lambda_{1} \int_{\Omega} u^{\alpha-1}(x) \phi(x) \mathrm{d} x, \quad \forall \phi \in W_{0}^{1, \alpha}(\Omega) . \tag{25}
\end{array}
$$

Consider $\phi(x)=\left(u(x)-u_{*}(s)\right)_{+} \in W_{0}^{1, \alpha}(\Omega)$. From 25), we deduce:

$$
\begin{equation*}
\sum_{i=1}^{N} \int_{\left\{u>u_{*}(s)\right\}} w_{i}^{*}(x) \frac{\partial u}{\partial x_{i}}(x) \mathrm{d} x=\lambda_{1} \int_{\Omega} u^{\alpha-1}(x)\left(u(x)-u_{*}(s)\right)_{+} \mathrm{d} x . \tag{26}
\end{equation*}
$$

We set
$E_{\leqslant 1}:=\left\{u>u_{*}(s)\right\} \cap\left\{\left|\frac{\partial u}{\partial x_{i}}\right| \leqslant 1\right\} \quad$ and $E_{>1}:=\left\{u>u_{*}(s)\right\} \cap\left\{\left|\frac{\partial u}{\partial x_{i}}\right|>1\right\}$.

We then have:

$$
\begin{aligned}
\Xi & :=\sum_{i=1}^{N} \int_{\left\{u>u_{*}(s)\right\}} w_{i}^{*}(x) \frac{\partial u}{\partial x_{i}}(x) \mathrm{d} x \\
& \geqslant \tau \sum_{i=1}^{N} \int_{\left\{u>u_{*}(s)\right\}} \varphi_{i}\left(x, \frac{\partial u}{\partial x_{i}}(x)\right) \mathrm{d} x \\
& =\tau \sum_{i=1}^{N} \int_{E_{\leqslant 1}}\left|\frac{\partial u}{\partial x_{i}}\right|^{\tau}(x) \mathrm{d} x+\tau \sum_{i=1}^{N} \int_{E_{>1}}\left|\frac{\partial u}{\partial x_{i}}\right|^{\alpha}(x) \mathrm{d} x \\
& \geqslant \tau \sum_{i=1}^{N} \int_{\left\{u>u_{*}(s)\right\}}\left|\frac{\partial u}{\partial x_{i}}\right|^{\alpha}(x) \mathrm{d} x-\tau \sum_{i=1}^{N} \int_{E_{\leqslant 1}}\left|\frac{\partial u}{\partial x_{i}}\right|^{\alpha}(x) \mathrm{d} x \\
& \geqslant \tau \sum_{i=1}^{N} \int_{\left\{u>u_{*}(s)\right\}}\left|\frac{\partial u}{\partial x_{i}}\right|^{\alpha}(x) \mathrm{d} x-c_{1},
\end{aligned}
$$

where $c_{1}=N \cdot \tau \cdot|\Omega|$ is a positive constant independent of $u$.
We know that there exists $c_{2}=c_{2}(N, \alpha)$, a positive constant depending on $N$ and $\alpha$, such that:

$$
\begin{equation*}
\sum_{i=1}^{N}\left|\frac{\partial u}{\partial x_{i}}\right|^{\alpha} \geqslant c_{2}\left(\sum_{i=1}^{N}\left|\frac{\partial u}{\partial x_{i}}\right|^{2}\right)^{\frac{\alpha}{2}}=c_{2}|\nabla u|^{\alpha} \tag{27}
\end{equation*}
$$

Hence

$$
\begin{equation*}
\sum_{i=1}^{N} \int_{\left\{u>u_{*}(s)\right\}} w_{i}^{*}(x) \frac{\partial u}{\partial x_{i}}(x) \mathrm{d} x \geqslant \tau \cdot c_{2} \int_{\left\{u>u_{*}(s)\right\}}|\nabla u|^{\alpha} \mathrm{d} x-c_{1} . \tag{28}
\end{equation*}
$$

Therefore, (28) and (26) imply that

$$
\begin{equation*}
\tau \cdot c_{2} \int_{\left\{u>u_{*}(s)\right\}}|\nabla u|^{\alpha} \mathrm{d} x \leqslant \lambda_{1} \int_{\Omega} u^{\alpha-1}(x)\left(u(x)-u_{*}(s)\right)_{+} \mathrm{d} x+c_{1} \tag{29}
\end{equation*}
$$

But $u \in W_{0}^{1, \alpha}(\Omega)$ and $u \geqslant 0$, thus $u_{*} \in W_{l o c}^{1,1}\left(\Omega_{*}\right)$. By using Lemma 3.3, we deduce from (29) that:

$$
\begin{aligned}
\left(|\nabla u|^{\alpha}\right)_{* u}(s) & \leqslant \lambda_{2}\left(-u_{*}^{\prime}(s)\right) \int_{0}^{s}\left(u^{\alpha-1}\right)_{* u}(\sigma) d \sigma \\
& \leqslant \lambda_{2}\left(-u_{*}^{\prime}(s)\right) \int_{0}^{s}\left(u^{\alpha-1}\right)_{*}(\sigma) d \sigma \\
& \leqslant \lambda_{2}\left(-u_{*}^{\prime}(s)\right) \int_{0}^{s}\left(u_{*}\right)^{\alpha-1}(\sigma) d \sigma
\end{aligned}
$$

where $\lambda_{2}=\frac{\lambda_{1}}{\tau \cdot c_{2}}$.

Proposition 7.1 Let $u \in W_{0}^{1, \alpha}(\Omega), u \geqslant 0$ verifying (24), then there exist $c_{6}>0$ and $c_{7}>0$ two positive constants such that, for a.e. $\left.s \in \Omega_{*}=\right] 0,|\Omega|[$, one has

$$
\begin{equation*}
|\nabla u|_{* u}(s) \leqslant c_{6} s^{-\frac{N-1}{N(\alpha-1)}}\left(\int_{0}^{s} u_{*}^{\alpha-1}(t) d t\right)^{\frac{1}{\alpha-1}}+c_{7} . \tag{30}
\end{equation*}
$$

Proof. Thanks to the Hölder inequality for the relative rearrangement, we have (see 14 )

$$
\begin{equation*}
\left[|\nabla u|_{* u}\right]^{\alpha}(s) \leqslant\left(|\nabla u|^{\alpha}\right)_{* u}(s), \quad \text { a.e. on } s . \tag{31}
\end{equation*}
$$

Using Theorem 3.4 it follows

$$
\begin{aligned}
{\left[|\nabla u|_{* u}\right]^{\alpha}(s) } & \leqslant \lambda_{1 N}\left(-\frac{d u_{*}}{d s}(s)\right) \int_{0}^{s} u_{*}^{\alpha-1}(t) d t+c_{2} \\
& \leqslant \frac{\lambda_{1 N}}{N \omega_{N}^{\frac{1}{N}}} s^{\frac{1}{N}-1} \int_{0}^{s} u_{*}^{\alpha-1}(t) d t \cdot|\nabla u|_{* u}(s)+c_{2} .
\end{aligned}
$$

Using Young inequality, we also have:

$$
\begin{equation*}
\left[|\nabla u|_{* u}\right]^{\alpha}(s) \leqslant c_{4} s^{\alpha^{\prime}\left(\frac{1}{N}-1\right)}\left(\int_{0}^{s} u_{*}^{\alpha-1}(t) d t\right)^{\alpha^{\prime}}+c_{5} \tag{32}
\end{equation*}
$$

where $\alpha^{\prime}$ is such that $\frac{1}{\alpha}+\frac{1}{\alpha^{\prime}}=1$.
This implies that

$$
\begin{equation*}
|\nabla u|_{* u}(s) \leqslant c_{6} s^{\frac{\alpha^{\prime}}{\alpha}\left(\frac{1}{N}-1\right)}\left(\int_{0}^{s} u_{*}^{\alpha-1}(t) d t\right)^{\frac{\alpha^{\prime}}{\alpha}}+c_{7} \tag{33}
\end{equation*}
$$

Thus, one has

$$
\begin{equation*}
|\nabla u|_{* u}(s) \leqslant c_{6} s^{\frac{1}{\alpha-1}\left(\frac{1}{N}-1\right)}\left(\int_{0}^{s} u_{*}^{\alpha-1}(t) d t\right)^{\frac{1}{\alpha-1}}+c_{7} \tag{34}
\end{equation*}
$$

Proposition 7.2 Under the same conditions as for Proposition 7.1. if $u \in L^{r}(\Omega)$ for $r>\frac{N}{\alpha^{\prime}}$ and $\frac{1}{\alpha}+\frac{1}{\alpha^{\prime}}=1$, then $u \in L^{\infty}(\Omega)$.

Proof. By Hölder inequality (for $\beta=\frac{r}{r-\alpha+1}$ and $\beta^{\prime}=\frac{r}{\alpha-1}$ ), one has

$$
\begin{aligned}
\left(\int_{0}^{s} u_{*}^{\alpha-1}(t) d t\right)^{\frac{1}{\alpha-1}} & \leqslant\left[s^{\frac{1}{\beta}} \cdot\left(\int_{0}^{|\Omega|} u_{*}^{(\alpha-1) \beta^{\prime}}(t) d t\right)^{\frac{1}{\beta^{\prime}}}\right]^{\frac{1}{\alpha-1}} \\
& \leqslant s^{\frac{1}{\alpha-1}-\frac{1}{r}} \cdot\left(\int_{0}^{|\Omega|} u_{*}^{r}(t) d t\right)^{\frac{1}{r}}
\end{aligned}
$$

Property 3.1 shows that

$$
\begin{equation*}
\left(\int_{0}^{s} u_{*}^{\alpha-1}(t) d t\right)^{\frac{1}{\alpha-1}} \leqslant s^{\frac{1}{\alpha-1}-\frac{1}{r}} \cdot\|u\|_{L^{r}(\Omega)} \tag{35}
\end{equation*}
$$

Using Theorem 3.4 and (34), one deduces

$$
\begin{equation*}
-u_{*}^{\prime}(s) \leqslant \frac{s^{\frac{1}{N}-1}}{N \omega_{N}^{\frac{1}{N}}}\left[c_{6} s^{\frac{1}{\alpha-1}\left(\frac{1}{N}-1\right)}\left(\int_{0}^{s} u_{*}^{\alpha-1}(t) d t\right)^{\frac{1}{\alpha-1}}+c_{7}\right] . \tag{36}
\end{equation*}
$$

From relations (35) and (36), we obtain

$$
-u_{*}^{\prime}(s) \leqslant c_{8} s^{\left(\frac{1}{N}-1\right)}\left[1+\frac{1}{\alpha-1}\right]+\frac{1}{\alpha-1}-\frac{1}{r} \cdot\|u\|_{L^{r}(\Omega)}+c_{9} s^{\frac{1}{N}-1} .
$$

The exponent $\left(\frac{1}{N}-1\right)\left[1+\frac{1}{\alpha-1}\right]+\frac{1}{\alpha-1}-\frac{1}{r}$, denoted $\gamma$, should verify:

$$
\begin{aligned}
\gamma+1>0 & \Longleftrightarrow\left(\frac{1}{N}-1\right)\left[1+\frac{1}{\alpha-1}\right]+\frac{1}{\alpha-1}-\frac{1}{r}>-1 \\
& \Longleftrightarrow r>\frac{N}{\alpha^{\prime}}
\end{aligned}
$$

For all $\sigma, t \in \Omega_{*}$, one has

$$
\begin{aligned}
\left|u_{*}(\sigma)-u_{*}(t)\right| & \leqslant c_{8} \cdot\|u\|_{L^{r}(\Omega)} \int_{0}^{|\Omega|} s^{\gamma} d s+c_{9} \int_{0}^{|\Omega|} s^{\frac{1}{N}-1} d s \\
& \leqslant c_{8} \frac{|\Omega|^{\gamma+1}}{\gamma+1} \cdot\|u\|_{L^{r}(\Omega)}+c_{9} \frac{|\Omega|^{\frac{1}{N}}}{\frac{1}{N}} .
\end{aligned}
$$

Since $u \in W_{0}^{1, \alpha}(\Omega)$ and $u \geqslant 0$, then we have $u_{*}(|\Omega|)=0$. In particular, for all $\sigma \in \Omega_{*}$, one deduces

$$
\begin{equation*}
\left|u_{*}(\sigma)\right| \leqslant c_{10}|\Omega|^{\gamma+1} \cdot\|u\|_{L^{r}(\Omega)}+c_{11}|\Omega|^{\frac{1}{N}} . \tag{37}
\end{equation*}
$$

Hence

$$
\begin{equation*}
\|u\|_{L^{\infty}(\Omega)} \leqslant c_{12} \cdot\|u\|_{L^{r}(\Omega)}+c_{13} . \tag{38}
\end{equation*}
$$

We point out certain situations in which the condition $u \in L^{r}(\Omega), r>\frac{\square}{\alpha^{\prime}}$ is satisfied. For this purpose, consider $1<\alpha<N$. Thus, we have

$$
\begin{equation*}
\alpha^{*}=\frac{N \alpha}{N-\alpha}>\frac{N}{\alpha^{\prime}} \Longleftrightarrow 2 \alpha^{2}-(N+1) \alpha+N>0 . \tag{39}
\end{equation*}
$$

The discriminant of the last quadratic equation is given by

$$
\Delta_{N}=(N+1)^{2}-8 N=(N-3)^{2}-8
$$

If the discriminant is positive, then there are two distinct roots

$$
\begin{equation*}
\alpha_{N}^{-}=\frac{N+1-\sqrt{\Delta_{N}}}{4} \quad \text { and } \quad \alpha_{N}^{+}=\frac{N+1+\sqrt{\Delta_{N}}}{4} . \tag{40}
\end{equation*}
$$

Proposition 7.3 If $1 \leqslant N \leqslant 5$, then $\alpha^{*}>\frac{N}{\alpha^{\prime}}$ and $u \in L^{\infty}(\Omega)$.
Proof. Since $1 \leqslant N \leqslant 5$, then $\Delta_{N}<0$. By (39), we deduce that $\alpha^{*}>\frac{N}{\alpha^{\prime}}$.
This implies the existence of a constant $r>0$ such that $\alpha^{*}>r>\frac{N}{\alpha^{\prime}}$.
By Sobolev embedding, we deduce

$$
W_{0}^{1, \alpha}(\Omega) \subset L^{\alpha^{*}}(\Omega) \subset L^{r}(\Omega) .
$$

Proposition 7.2 gives the result.
Proposition 7.4 If $N \geqslant 6$, then there are two distinct roots $\alpha_{N}^{-}$and $\alpha_{N}^{+}$such that $1<\alpha_{N}^{-}<\alpha_{N}^{+}<N$.

Proof. If $N \geqslant 6$, then $\Delta_{N}>0$ and the roots are given by 40 .
We also have

$$
\begin{aligned}
1<\alpha_{N}^{-} & \Longleftrightarrow 4<N+1-\sqrt{(N-3)^{2}-8} \\
& \Longleftrightarrow \sqrt{(N-3)^{2}-8}<N-3 \\
& \Longleftrightarrow-8<0 .
\end{aligned}
$$

Moreover, one has

$$
\begin{aligned}
\alpha_{N}^{+}<N & \Longleftrightarrow N+1+\sqrt{(N-3)^{2}-8}<4 N \\
& \Longleftrightarrow(N-3)^{2}-8<(3 N-1)^{2} \\
& \Longleftrightarrow 0<8 N^{2} .
\end{aligned}
$$

Proposition 7.5 Assume that $N \geqslant 6$. If $1<\alpha<\alpha_{N}^{-}$or $\alpha_{N}^{+}<\alpha<N$, then $u \in L^{\infty}(\Omega)$.

Proof. By Proposition 7.4, we know that $1<\alpha_{N}^{-}<\alpha_{N}^{+}<N$. In addition, if $\alpha_{N}^{+}<\alpha<N$, then $\alpha^{*}>\frac{N}{\alpha^{\prime}}$, we conclude that $u \in L^{\infty}(\Omega)$ (see the proof of Proposition 7.3. If $1<\alpha<\alpha_{N}^{-}$, the same argument holds.
Using now Lemmas $7.1,7.2$ and Propositions $7.1-7.5$, the proof of Theorem 7.1 is complete.

In the univalued case, we can refine the calculations and provide details of the constants. The method used for the $p$-Laplacian is based on the PoincaréSobolev and interpolation inequalities.

Theorem 7.2 Let $\lambda_{1}, u_{1}$ be the first eigenvalue and eigenfunction of $\Delta_{p}$ :

$$
\begin{cases}-\Delta_{p} u_{1}=\lambda_{1} u_{1}^{p-1}>0, & \text { for } 1<p<N,  \tag{41}\\ \int_{\Omega} u_{1}^{p} \mathrm{~d} x=1, & \text { and } u_{1} \in W_{0}^{1, p}(\Omega)\end{cases}
$$

Then,

$$
\max _{\bar{\Omega}} u_{1} \leqslant\left(\frac{B_{p^{*}}^{\frac{1}{p^{*}}}}{N \omega_{N}^{\frac{1}{N}}}\right)^{\frac{\theta}{\theta-1}}\left(\frac{\lambda_{1}}{p}\right)^{\frac{\theta}{p(\theta-1)}}
$$

where $\theta=\frac{p^{*}}{p}, \lambda_{1}=\inf \left\{\int_{\Omega}|\nabla v|^{p} \mathrm{~d} x: \int_{\Omega} v^{p} \mathrm{~d} x=1\right\}, p^{*}=\frac{N p}{N-p}, B_{p^{*}}$ is the Bliss constant 14 and $\omega_{N}$ is the Lebesgue measure of the unit ball in $\mathbb{R}^{N}$.
Proof. Let $J$ be as follows

$$
\begin{aligned}
J & =\int_{\Omega}\left|\nabla u_{1}\right|^{p-2} \nabla u_{1} \cdot \nabla\left(u_{1}^{m+1}\right) \mathrm{d} x=(m+1) \int_{\Omega}\left|\nabla u_{1}\right|^{p-2} \nabla u_{1} \cdot\left(\nabla u_{1} u_{1}^{m}\right) \mathrm{d} x \\
& =(m+1) \int_{\Omega}\left|\nabla u_{1}\right|^{p} \cdot u_{1}^{m} \mathrm{~d} x=(m+1) \int_{\Omega}\left|\nabla u_{1} \cdot u_{1}^{\frac{m}{p}}\right|^{p} \mathrm{~d} x
\end{aligned}
$$

Since we have

$$
\nabla u_{1}^{\frac{m+p}{p}}=\frac{m+p}{p} \nabla u_{1} \cdot u_{1}^{\frac{m}{p}},
$$

we conclude

$$
\begin{equation*}
J=\frac{p(m+1)}{m+p} \int_{\Omega}\left|\nabla u_{1}^{\frac{m+p}{p}}\right|^{p} \mathrm{~d} x \tag{42}
\end{equation*}
$$

By (41), $J$ can be written as

$$
J=\lambda_{1} \int_{\Omega} u_{1}^{p-1} \cdot u_{1}^{m+1} \mathrm{~d} x=\lambda_{1} \int_{\Omega} u_{1}^{m+p} \mathrm{~d} x
$$

The Poincaré-Sobolev inequality (see 14 ) implies:

$$
\begin{aligned}
\left(\int_{\Omega} u_{1}^{\frac{p^{*}(m+p)}{p}} \mathrm{~d} x\right)^{\frac{1}{p^{*}}} & \leqslant \frac{B_{p^{*}}^{\frac{1}{p^{*}}}}{N \omega_{N}^{\frac{1}{N}}}\left(\int_{\Omega}\left|\nabla u_{1}^{\frac{m+p}{p}}\right|^{p}\right)^{\frac{1}{p}} \\
& =\frac{B_{p^{*}}^{\frac{1}{p^{*}}}}{N \omega_{N}^{\frac{1}{N}}}\left(\lambda_{1} \frac{m+p}{p(m+1)}\right)^{\frac{1}{p}}\left(\int_{\Omega} u_{1}^{m+p} \mathrm{~d} x\right)^{\frac{1}{p}}
\end{aligned}
$$

from which we obtain

$$
\begin{equation*}
\left\|u_{1}\right\|_{L^{\theta(m+p)}(\Omega)}^{\frac{m+p}{p}} \leqslant \frac{B_{p^{*}}^{\frac{1}{p^{*}}}}{N \omega_{N}^{\frac{1}{N}}}\left(\lambda_{1} \frac{m+p}{p(m+1)}\right)^{\frac{1}{p}}\left\|u_{1}\right\|_{L^{m+p}(\Omega)}^{\frac{m+p}{p}} \tag{43}
\end{equation*}
$$

Therefore,

$$
\begin{equation*}
\left\|u_{1}\right\|_{L^{\theta(m+p)}(\Omega)} \leqslant\left(\frac{B_{p^{*}}^{\frac{1}{p^{*}}}}{N \omega_{N}^{\frac{1}{N}}}\right)^{\frac{p}{m+p}}\left(\lambda_{1} \frac{m+p}{p(m+1)}\right)^{\frac{1}{m+p}}\left\|u_{1}\right\|_{L^{m+p}(\Omega)} \tag{44}
\end{equation*}
$$

Using an interpolation inequality (see 29]) for $0 \leqslant \eta \leqslant 1$, one has

$$
\begin{equation*}
\left\|u_{1}\right\|_{L^{m+p}(\Omega)} \leqslant\left\|u_{1}\right\|_{L^{p}}^{1-\eta} \cdot\left\|u_{1}\right\|_{L^{\theta(m+p)}}^{\eta} \quad \text { and } \frac{1}{m+p}=\frac{1-\eta}{p}+\frac{\eta}{\theta(m+p)} . \tag{45}
\end{equation*}
$$

The above equality leads to

$$
\begin{equation*}
\eta=\frac{\theta m}{\theta(m+p)-p}, \quad \text { and } \quad 1-\eta=\frac{p(\theta-1)}{\theta(m+p)-p} . \tag{46}
\end{equation*}
$$

Combining (44) and 45, we get

$$
\begin{equation*}
\left\|u_{1}\right\|_{L^{\theta(m+p)}} \leqslant\left(\frac{B_{p^{*}}^{\frac{1}{p^{*}}}}{N \omega_{N}^{\frac{1}{N}}}\right)^{\frac{p}{m+p}}\left(\lambda_{1} \frac{m+p}{p(m+1)}\right)^{\frac{1}{m+p}}\left\|u_{1}\right\|_{L^{p}}^{1-\eta} \cdot\left\|u_{1}\right\|_{L^{\theta(m+p)}}^{\eta} \tag{47}
\end{equation*}
$$

Thus, we have:

$$
\begin{equation*}
\left\|u_{1}\right\|_{L^{\theta(m+p)}} \leqslant\left(\frac{B_{p^{*}}^{\frac{1}{p^{*}}}}{N \omega_{N}^{\frac{1}{N}}}\right)^{\frac{p}{m+p} \cdot \frac{1}{1-\eta}}\left(\lambda_{1} \frac{m+p}{p(m+1)}\right)^{\frac{1}{m+p} \cdot \frac{1}{1-\eta}}\left\|u_{1}\right\|_{L^{p}} \tag{48}
\end{equation*}
$$

But

$$
\frac{1}{m+p} \cdot \frac{1}{1-\eta}=\frac{1}{p(\theta-1)} \cdot \frac{\theta(m+p)-p}{m+p} \underset{m \rightarrow+\infty}{ } \frac{\theta}{p(\theta-1)}
$$

This achieves the proof by letting $m \rightarrow+\infty$ in (48).
Remark 7.1 The $L^{\infty}$-regularity of the eigenfunctions of p-Laplacian is already known (see, for example, [30]).

## 8 Conclusion

In this paper, we treated eigenvalue problems related to $\bar{\rho}^{>}$-multivalued operators. We generalized the results of 1] and [2]. We studied the existence for a more general problem, by using the nonsmooth version of the Lagrange multiplier theorem. This existence result is then used to prove the $L^{\infty}$-regularity of the eigenvectors associated with the $\bar{\rho}^{>}$-multivalued Leray-Lions operators by using the relative rearrangement theory. We also proved an existence result for an eigenvalue problem in a resonant case near zero.

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